

Using and Understanding the Real-Time Cyclictest Benchmark

Cyclictest results are the most frequently cited real-time Linux metric. The core concept of Cyclictest is very simple. However the test options are very extensive. The meaning of Cyclictest results appear simple but are actually quite complex. This talk will explore and explain the complexities of Cyclictest. At the end of the talk, the audience will understand how Cyclictest results describe the potential real-time performance of a system.

What Cyclictest Measures

Latency of response to a stimulus.

external interrupt triggers (clock expires)

- possible delay until IRQs enabled
- IRQ handling
- cyclictest is woken
- possible delay until preemption enabled
- possible delay until cyclictest is highest priority
- possible delay until other process is preempted
- scheduler overhead

transfer control to cyclictest

What Cyclicttest Measures

Latency of response to a stimulus.

Causes of delay list on previous slide is simplified:

- order will vary
- may occur multiple times
- there are additional causes of delay

Many factors can increase latency

- additional external interrupts
- SMI
- processor emerging from sleep states
- cache migration of data used by woken process
- block on sleeping lock
  - lock owner gets priority boost
  - lock owner schedules
  - lock owner completes scheduled work
  - lock owner releases lock, loses priority boost

How Cyclictest Measures Latency

(Cyclictest Pseudocode)

The source code is nearly 3000 lines,
but the algorithm is trivial

Test Loop

```
clock_gettime(&now)
next = now + par->interval

while (!shutdown) {

    clock_nanosleep(&next)

    clock_gettime(&now)
    diff = calcdiff(now, next)

    # update stat-> min, max, total latency, cycles
    # update the histogram data

    next += interval
}
```

The Magic of Simple

This trivial algorithm captures all of the factors that contribute to latency.

Mostly. Caveats will follow soon.

Cyclictest Program

```
main() {  
  
    for (i = 0; i < num_threads; i++) {  
        pthread_create((timerthread))  
  
    while (!shutdown) {  
        for (i = 0; i < num_threads; i++)  
            print_stat((stats[i]), i)  
        usleep(10000)  
    }  
  
    if (histogram)  
        print_hist(parameters, num_threads)  
}
```

timerthread()

```
*timerthread(void *par) {  
    # thread set up  
  
    # test loop  
  
}
```

Thread Set Up

```
stat = par->stats;  
pthread_setaffinity_np((pthread_self()))  
setscheduler({par->policy, par->priority})  
sigprocmask((SIG_BLOCK))
```

Test Loop (as shown earlier)

```
clock_gettime(&now)
next = now + par->interval

while (!shutdown) {

    clock_nanosleep(&next)

    clock_gettime(&now)
    diff = calcdiff(now, next)

    # update stat-> min, max, avg, cycles
    # Update the histogram

    next += interval
}
```

Why show set up pseudocode?

The timer threads are not in lockstep from time zero.

Multiple threads will probably not directly impact each other.

The Magic of Simple

This trivial algorithm captures all of the factors that contribute to latency.

Mostly. Caveats, as promised.

Caveats

Measured maximum latency is a floor of the possible maximum latency

- Causes of delay may be partially completed when timer IRQ occurs
- Cyclicttest wakeup is on a regular cadence, may miss delay sources that occur outside the cadence slots

Caveats

Does not measure the IRQ handling path of the real RT application

- timer IRQ handling typically fully in IRQ context
- normal interrupt source IRQ handling:
  - irq context, small handler, wakes IRQ thread
  - IRQ thread eventually executes, wakes RT process

Caveats

Cyclictest may not exercise latency paths that are triggered by the RT application, or even non-RT applications

- SMI to fixup instruction errata
- stop_machine()
  - module load / unload
  - hotplug

Solution 1

Do not use cyclicttest. :-)

Instrument the RT application to measure latency

Solution 2

Run the normal RT application and non-RT applications as the system load

Run cyclicttest with a higher priority than the RT application to measure latency

Solution 2

Typical real time application will consist of multiple threads, with differing priorities and latency requirements

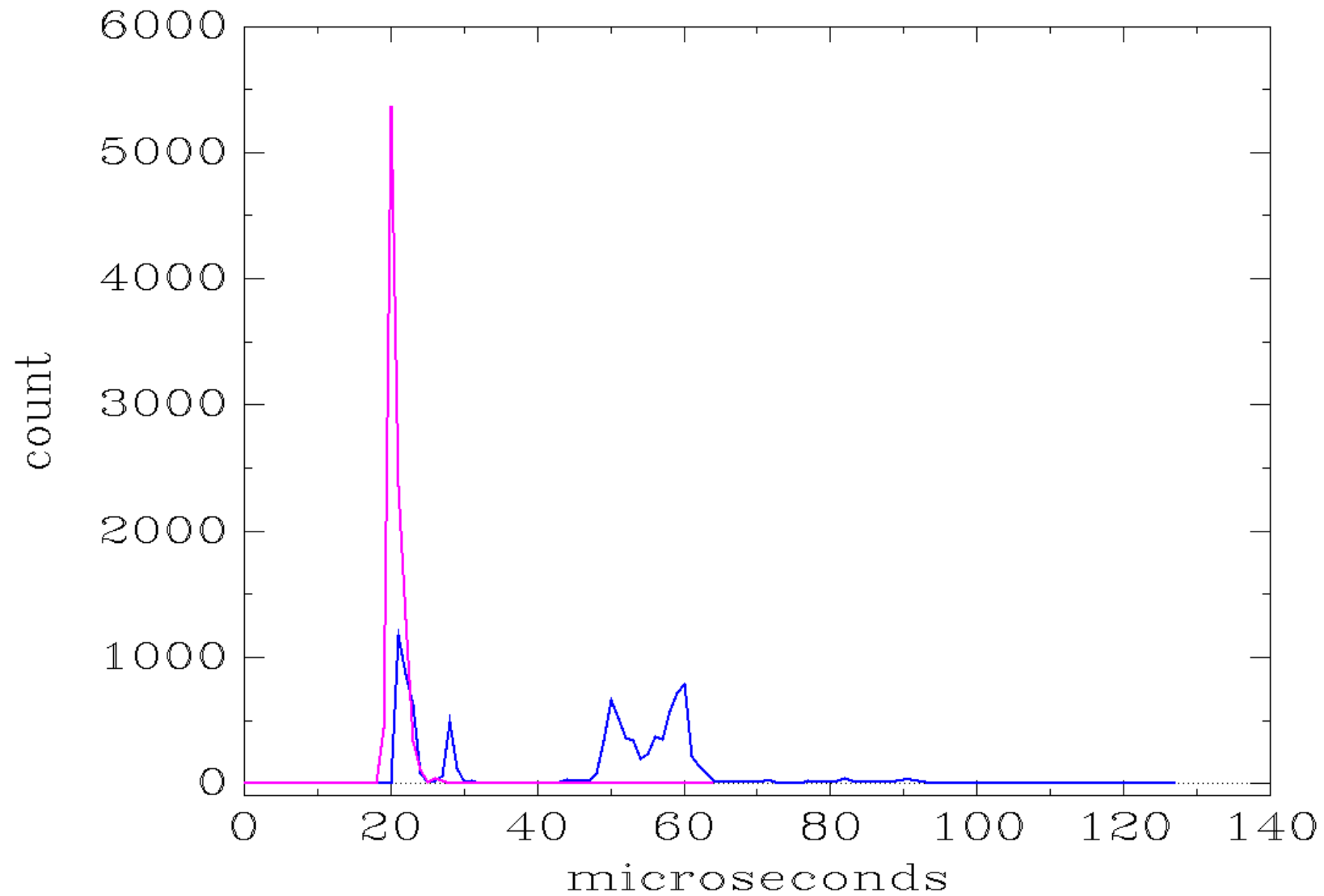
To capture latencies of each of the threads, run separate tests, varying the cyclicttest priority

Solution 2

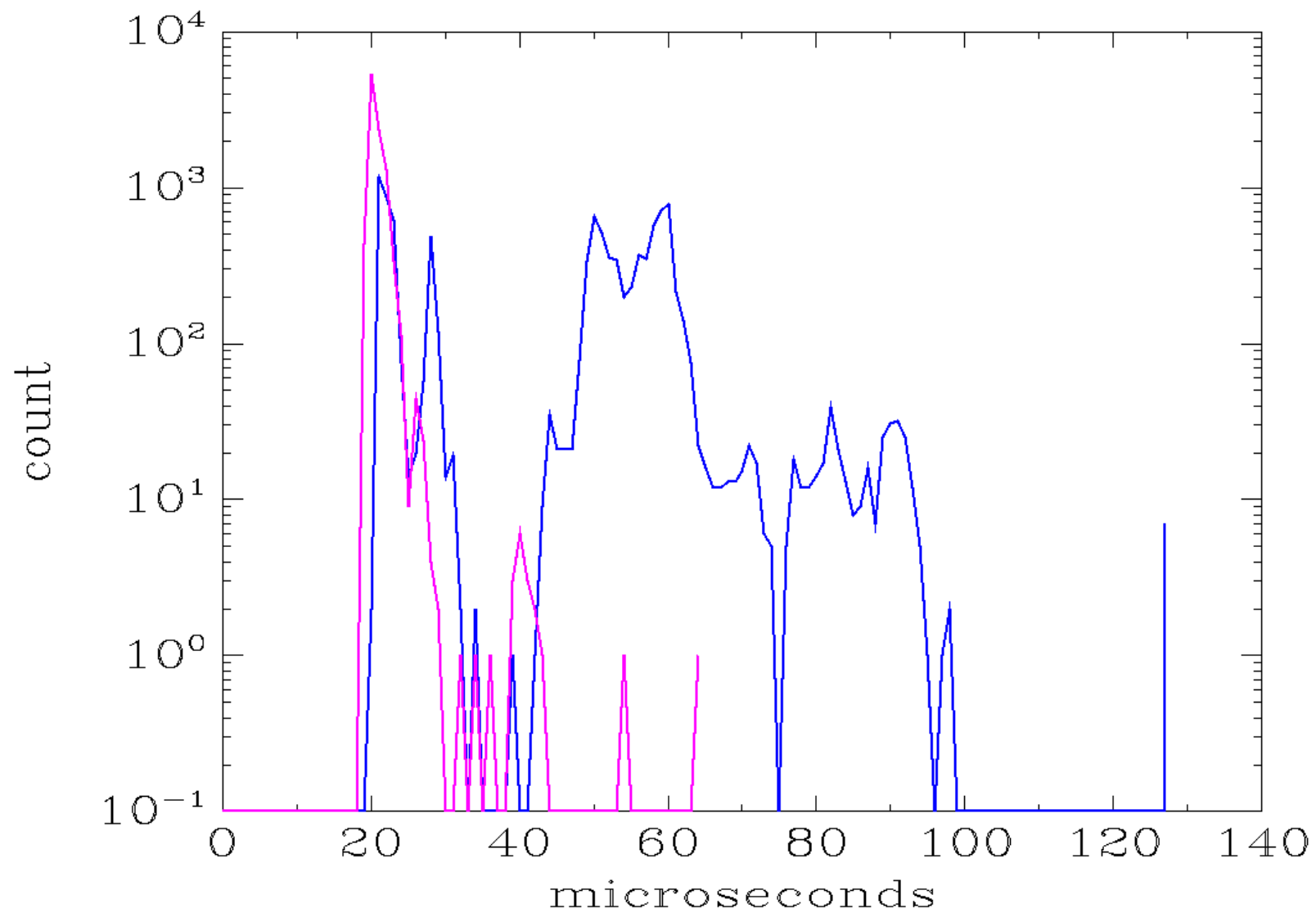
Example

<u>RT app thread</u>	<u>deadline constraint</u>	<u>latency constraint</u>	<u>RT app scheduler priority</u>	<u>cyclictest priority</u>
A	critical	80 usec	50	51
B	0.1% miss	100 usec	47	48

Cyclictest Latency
magenta: pri=51 blue: pri=48



Cyclictest Latency
magenta: pri=51 blue: pri=48



Aside:

Cyclictest output in these slides is edited to fit on the slides

Original:

```
$ cyclictest_0.85 -l1000000 -q -p80 -S
```

```
T: 0 ( 460) P:80 I:1000 C: 100000 Min: 37 Act: 43 Avg: 45 Max: 68  
T: 1 ( 461) P:80 I:1500 C: 66675 Min: 37 Act: 49 Avg: 42 Max: 72
```

Example of edit:

```
$ cyclictest_0.85 -l1000000 -q -p80 -S
```

```
T:0 I:1000 Min: 37 Avg: 45 Max: 68  
T:1 I:1500 Min: 37 Avg: 42 Max: 72
```

Cyclictest Command Line Options

Do I really care???

Can I just run it with the default options???

Do I really care???

```
$ cyclicttest_0.85 -l1000000 -q -p80
```

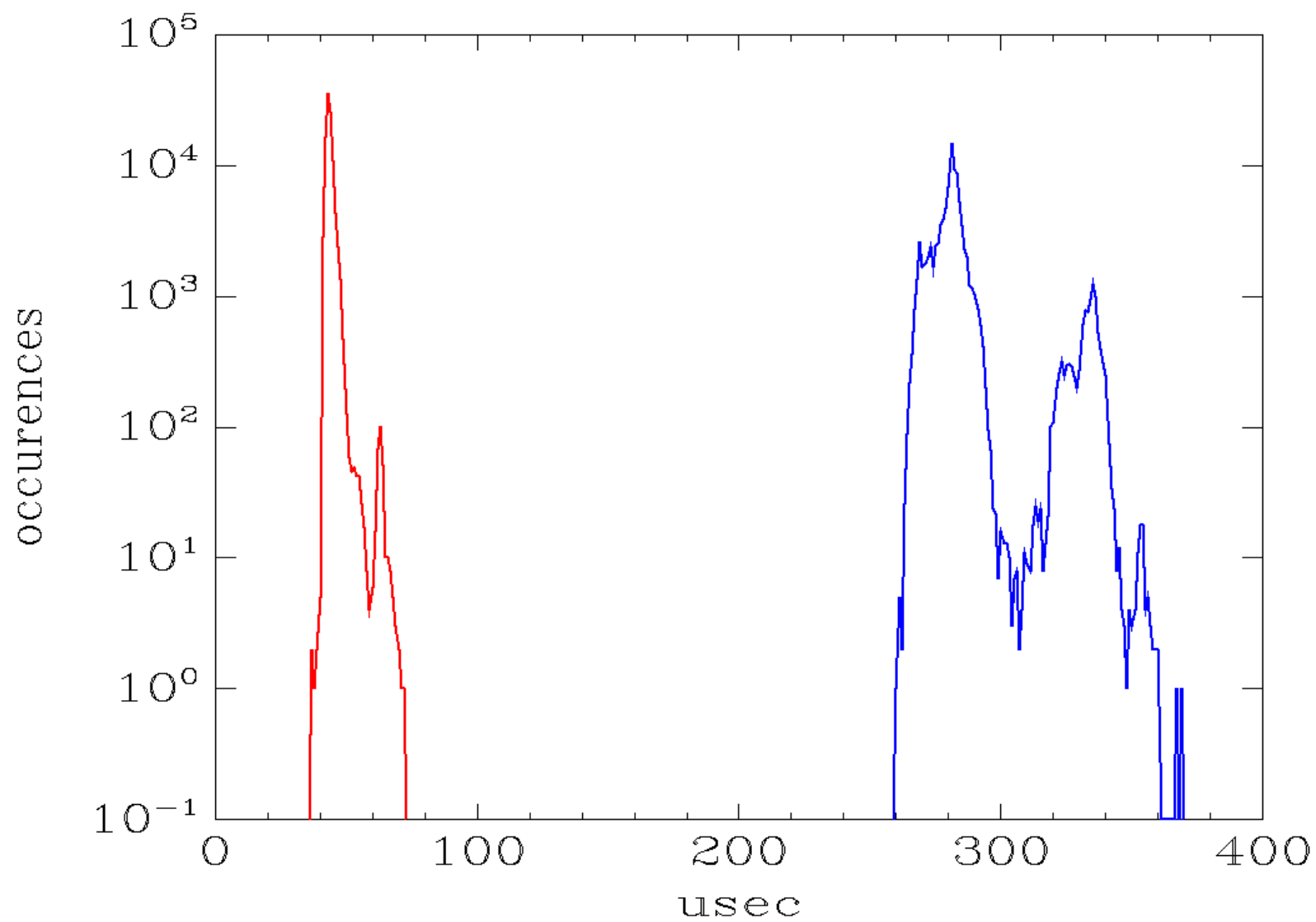
```
T:0   Min: 262   Avg: 281   Max: 337
```

```
$ cyclicttest_0.85 -l1000000 -q -p80 -n
```

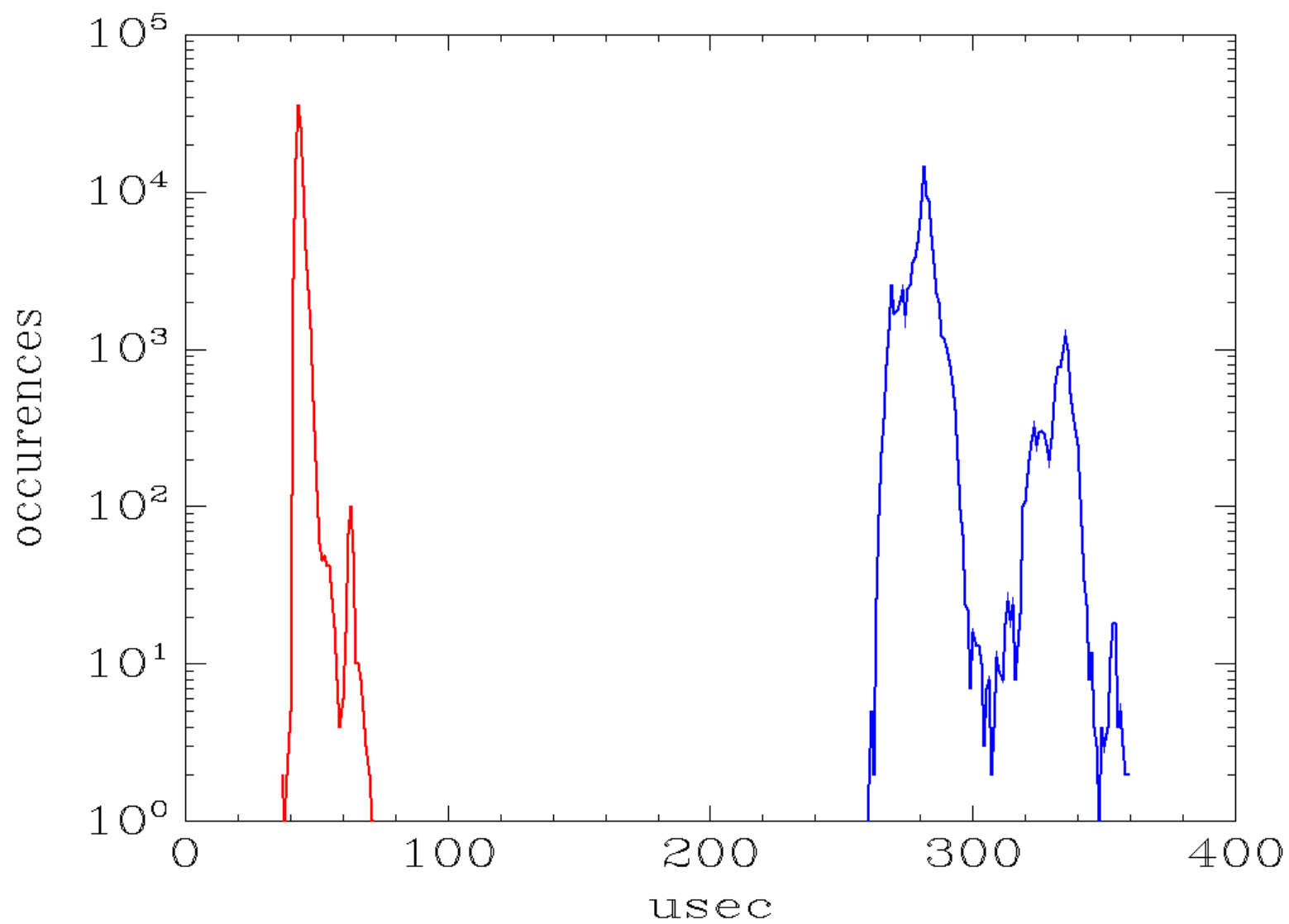
```
T:0   Min: 35   Avg: 43   Max: 68
```

-l1000000	stop after 1000000 loops
-q	quiet
-p80	priority 80, SCHED_FIFO
-n	use clock_nanosleep() instead of nanosleep()

red: clock_nanosleep() blue: nanosleep()
thread: 0



red: clock_nanosleep()   blue: nanosleep()
thread: 0



Impact of Options

More examples

Be somewhat skeptical of maximum latencies due to the short test duration.

Examples are:

100,000 loops

1,000,000 loops

Arbitrary choice of loop count. Need large values to properly measure maximum latency!!!

Priority of Real Time kernel threads for next two slides

PID	PPID	S	RTPRIO	CLS	CMD
3	2	S	1	FF	[ksoftirqd/0]
6	2	S	70	FF	[posixcpumr/0]
7	2	S	99	FF	[migration/0]
8	2	S	70	FF	[posixcpumr/1]
9	2	S	99	FF	[migration/1]
11	2	S	1	FF	[ksoftirqd/1]
353	2	S	50	FF	[irq/41-eth%d]
374	2	S	50	FF	[irq/46-mmci-pl1]
375	2	S	50	FF	[irq/47-mmci-pl1]
394	2	S	50	FF	[irq/36-uart-pl0]

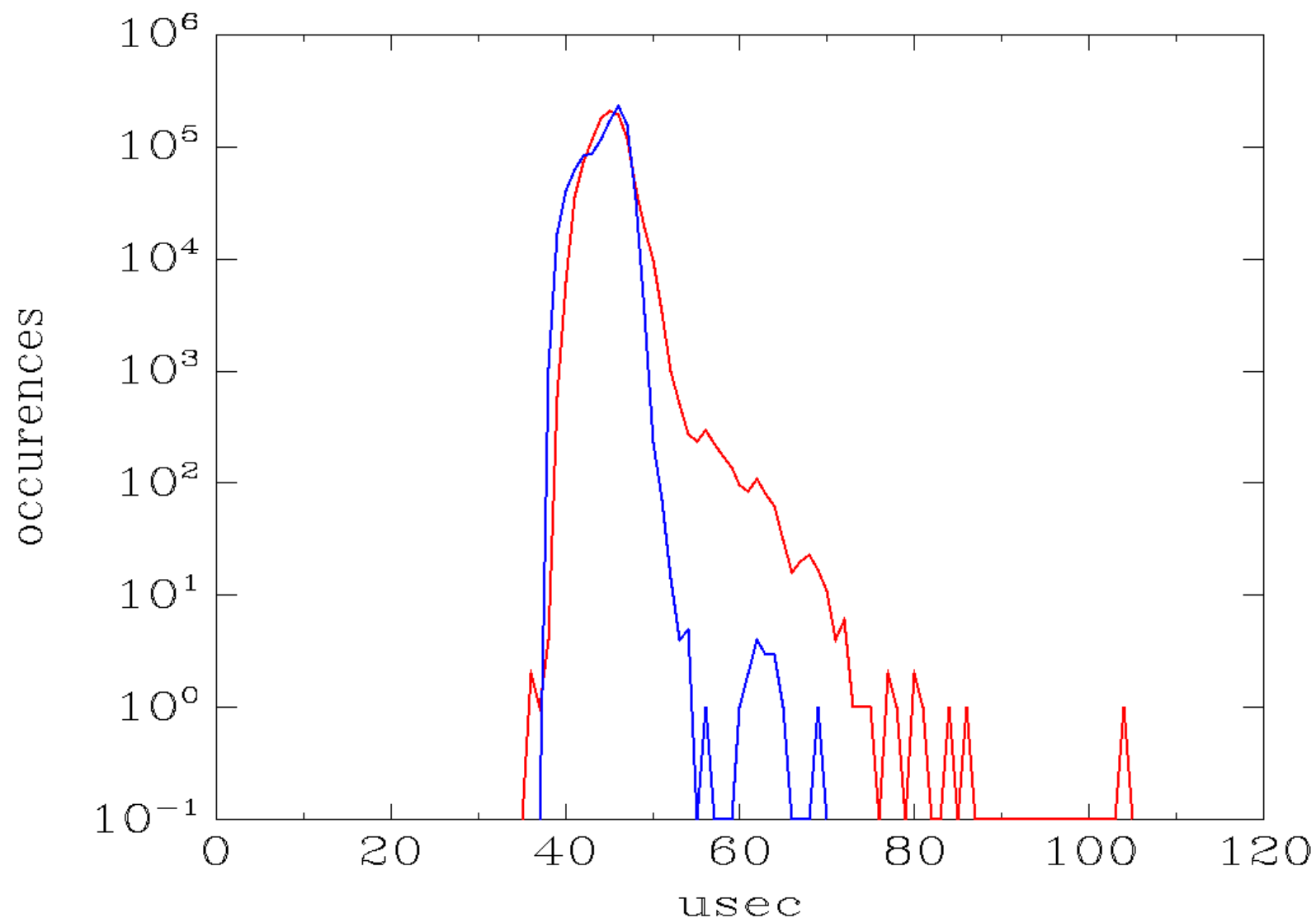
-1100000

T:0	Min: 128	Avg: 189	Max: 2699			<u>live update</u>
T:0	Min: 125	Avg: 140	Max: 472	-q		<u>no live update</u>
T:0	Min: 262	Avg: 281	Max: 337	-p80		<u>SCHED_FIFO 80</u>
T:0	Min: 88	Avg: 96	Max: 200	-n		<u>clock nanosleep</u>
T:0	Min: 246	Avg: 320	Max: 496	-q -p80 -a -t		<u>pinned</u>
T:1	Min: 253	Avg: 315	Max: 509			
T:0	Min: 35	Avg: 43	Max: 68	-q -p80 -n		<u>SCHED_FIFO, c n</u>
T:0	Min: 34	Avg: 44	Max: 71	-q -p80 -a -n		<u>pinned</u>
T:0	Min: 38	Avg: 43	Max: 119	-q -p80 -a -n -m		<u>mem locked</u>
T:0	Min: 36	Avg: 43	Max: 65	-q -p80 -t -n		<u>not pinned</u>
T:1	Min: 37	Avg: 45	Max: 78			
T:0	Min: 36	Avg: 44	Max: 91	-q -p80 -a -t -n		<u>pinned</u>
T:1	Min: 37	Avg: 45	Max: 111			
T:0	Min: 34	Avg: 44	Max: 94	-q -p80 -S		<u>=> -a -t -n</u>
T:1	Min: 34	Avg: 43	Max: 104			

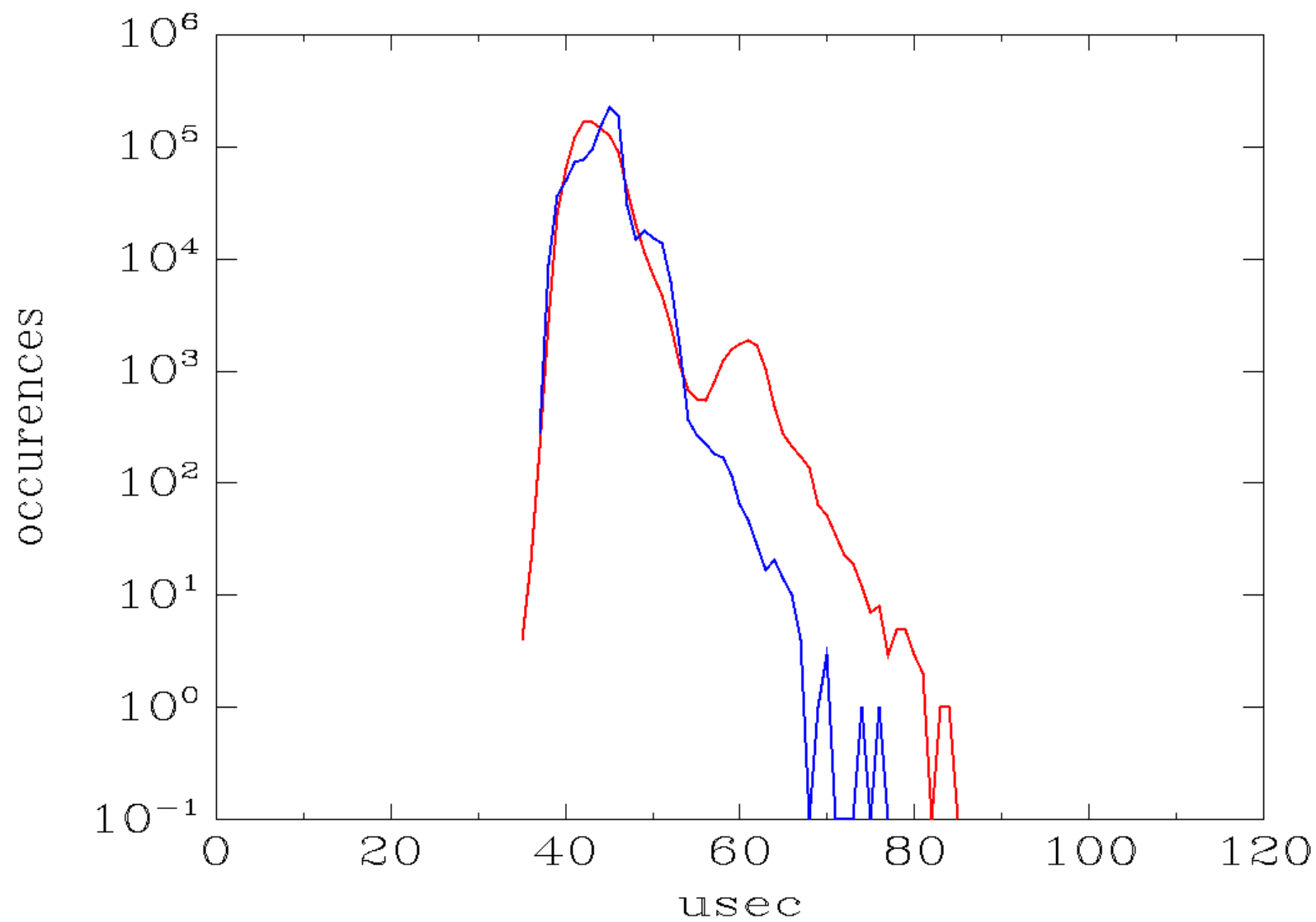
-11000000

T:0	Min: 123	Avg: 184	Max: 3814			<u>live update</u>
T:0	Min: 125	Avg: 150	Max: 860	-q		<u>no live update</u>
T:0	Min: 257	Avg: 281	Max: 371	-q -p80		<u>SCHED_FIFO 80</u>
T:0	Min: 84	Avg: 94	Max: 319	-q -n		<u>clock nanosleep</u>
T:0	Min: 247	Avg: 314	Max: 682	-q -p80 -a -t		<u>pinned</u>
T:1	Min: 228	Avg: 321	Max: 506			
T:0	Min: 38	Avg: 44	Max: 72	-q -p80 -n		<u>SCHED_FIFO, c n</u>
T:0	Min: 33	Avg: 42	Max: 95	-q -p80 -a -n		<u>pinned</u>
T:0	Min: 36	Avg: 42	Max: 144	-q -p80 -a -n -m		<u>mem locked</u>
T:0	Min: 36	Avg: 44	Max: 84	-q -p80 -t -n		<u>not pinned</u>
T:1	Min: 37	Avg: 45	Max: 94			
T:0	Min: 36	Avg: 43	Max: 87	-q -p80 -a -t -n		<u>pinned</u>
T:1	Min: 36	Avg: 43	Max: 91			
T:0	Min: 36	Avg: 43	Max: 141	-q -p80 -S		<u>=> -a -t -n</u>
T:1	Min: 34	Avg: 42	Max: 88			

blue: cpu pinned   red: cpu not pinned
thread: 0



blue: cpu pinned   red: cpu not pinned
thread: 1



Simple Demo -- SCHED_NORMAL

- single thread
- clock_nanosleep(), one thread per cpu, pinned
- clock_nanosleep(), one thread per cpu
- clock_nanosleep(), one thread per cpu, memory locked
- clock_nanosleep(), one thread per cpu, memory locked, non-interactive

What Are Normal Results?

What should I expect the data to look like for my system?

Examples of Maximum Latency

https://rt.wiki.kernel.org/index.php/CONFIG_PREEMPT_RT_Patch#Platforms_Test_and_in_Use_with_CONFIG_PREEMPT_RT

Platforms Tested and in Use with CONFIG_PREEMPT_RT

Comments sometimes include avg and max latency

table is usually stale

linux-rt-users email list archives

<http://vger.kernel.org/vger-lists.html#linux-rt-users>

Graphs of Maximum Latency

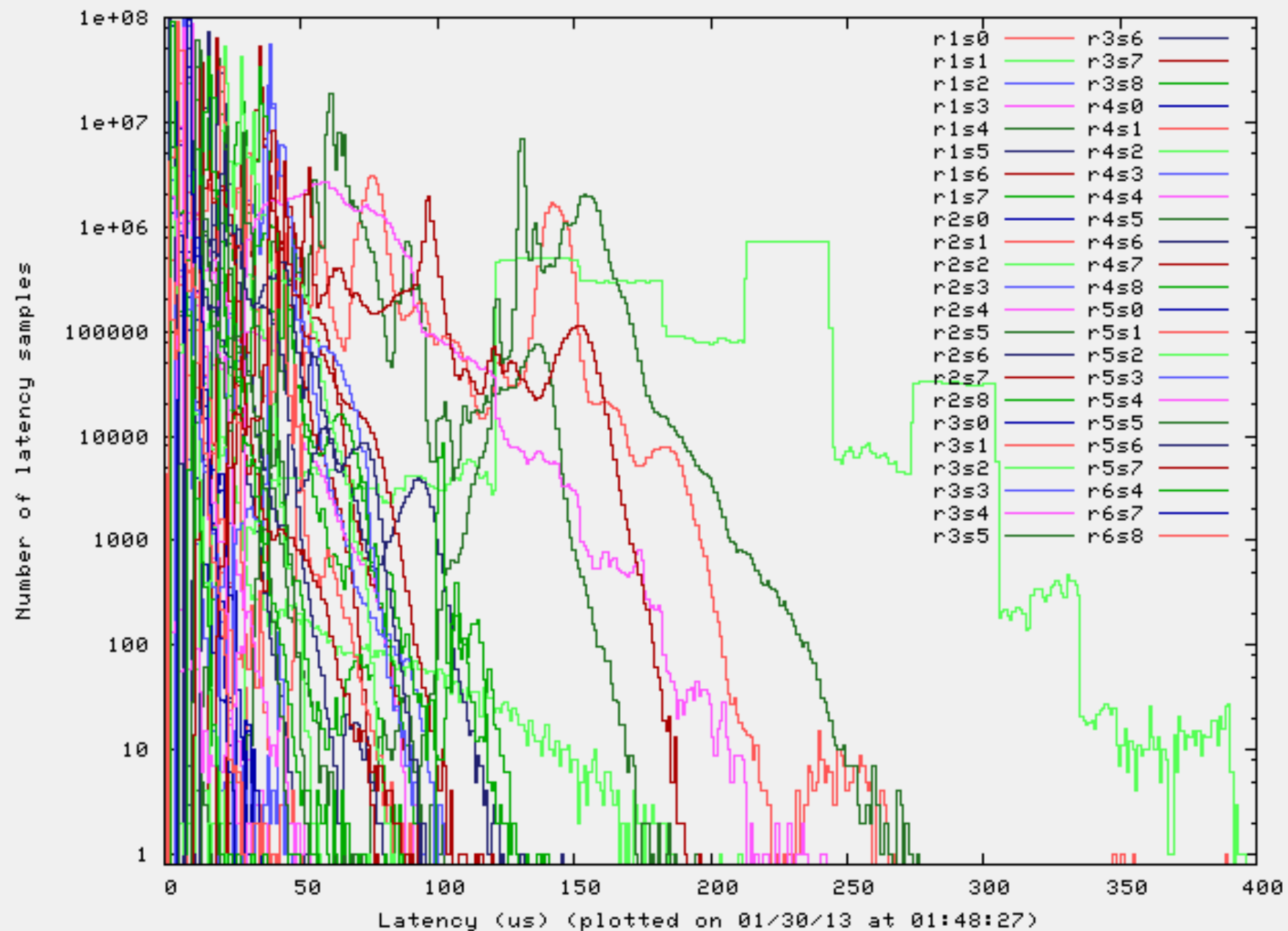
OSADL.org

Graphs for a wide variety of machines

List of test systems:

<https://www.osadl.org/Individual-system-data.qa-farm-data.0.html>

Latency of all RT systems under test



Full URL of previous graph

<https://www.osadl.org/Combined-latency-plot-of-all-RT-systems.qa-latencyplot-allrt.0.html?latencies=&showno=>

Typical command:

```
cyclictest -l1000000000 -m -Sp99 -i200 -h400 -q
```

OSADL Realtime QA Farm:

<https://www.osadl.org/QA-Farm-Realtime.qa-farm-about.0.html>

OSADL Latency plots:

<https://www.osadl.org/Latency-plots.latency-plots.0.html>

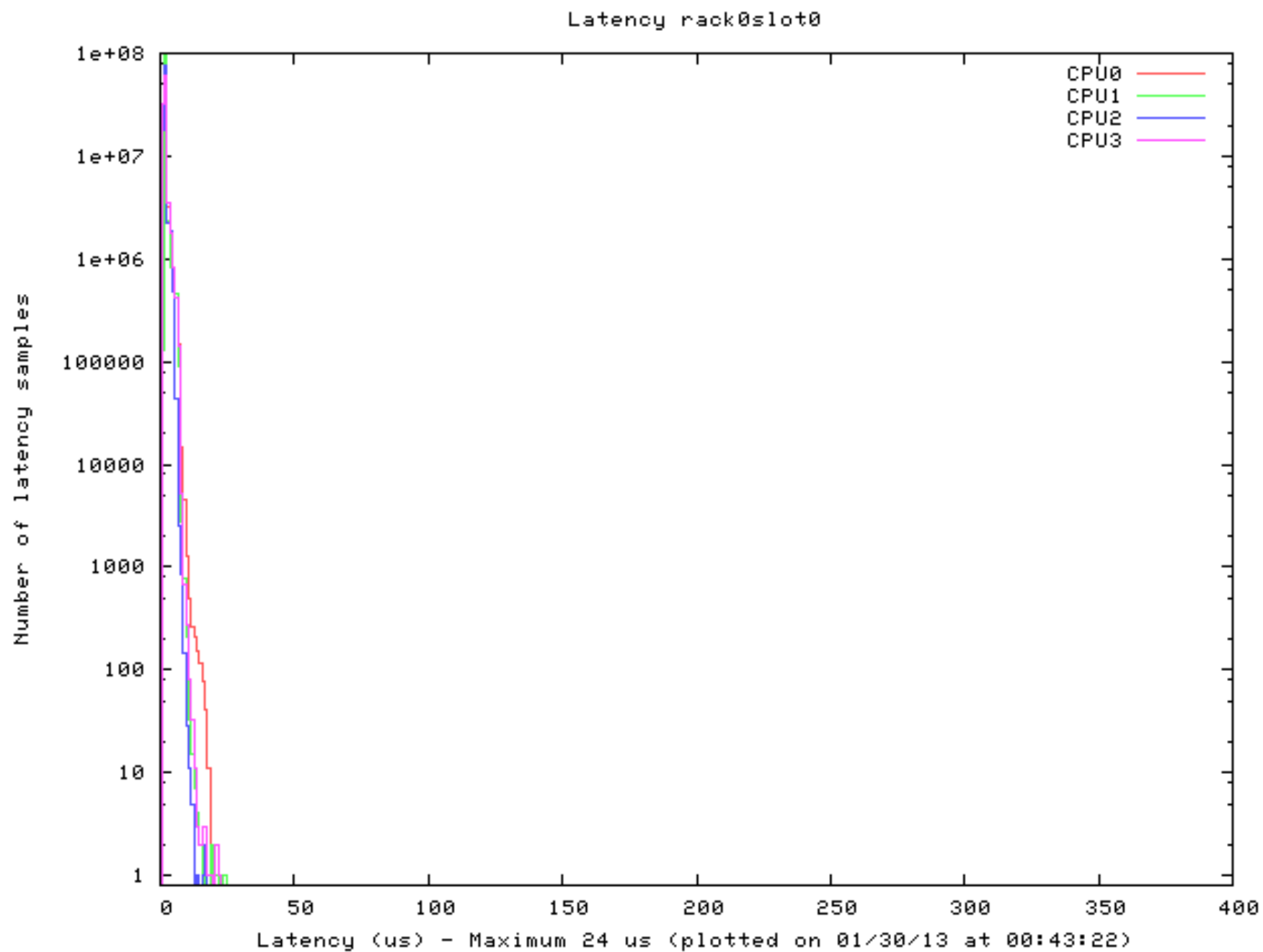
Additional OSADL Data

OSADL members have access to additional data, such as

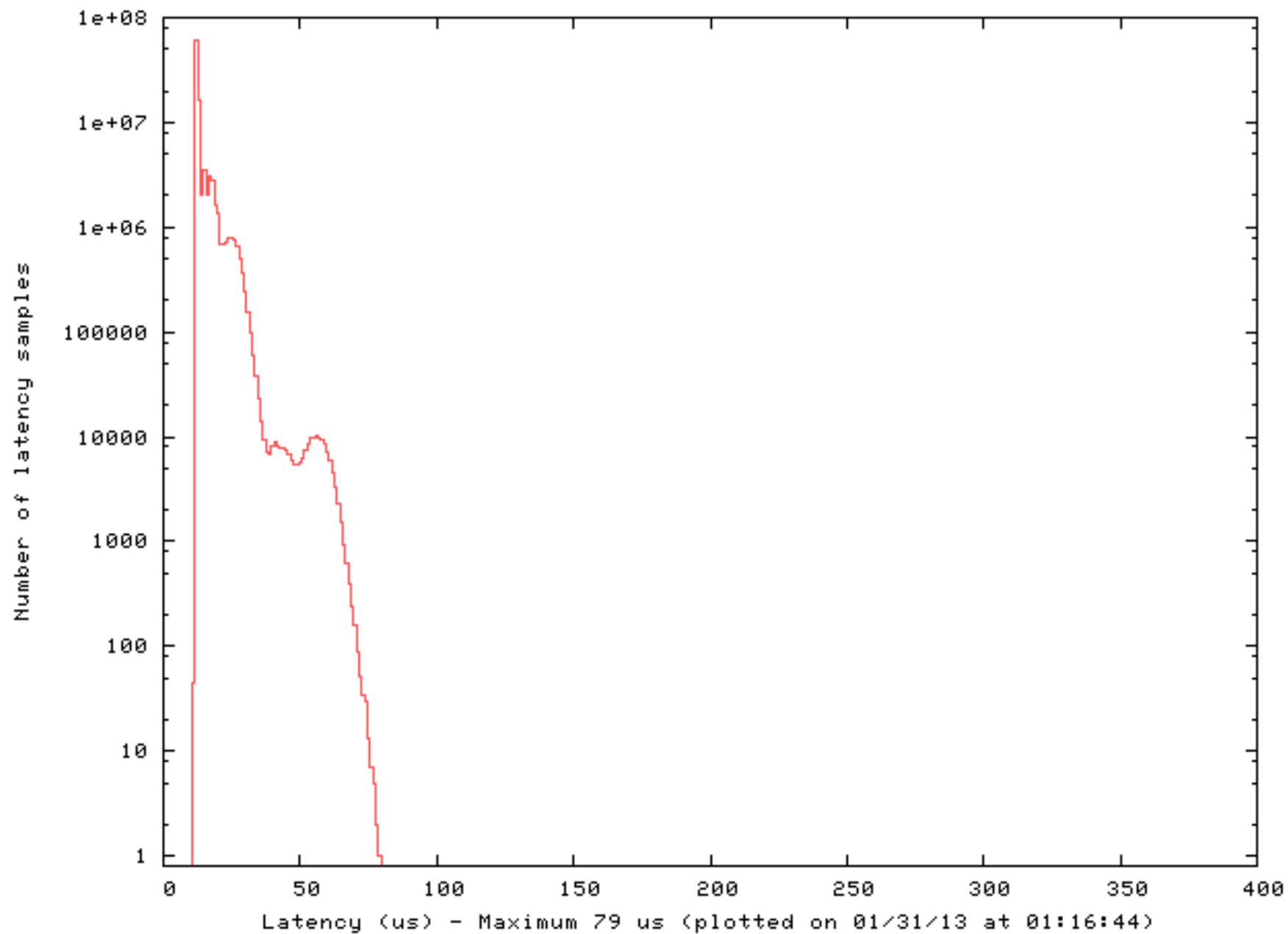
- the data used to create the graphs
- the latency graphs extended in a third dimension, showing all test runs

Some Random Individual Systems

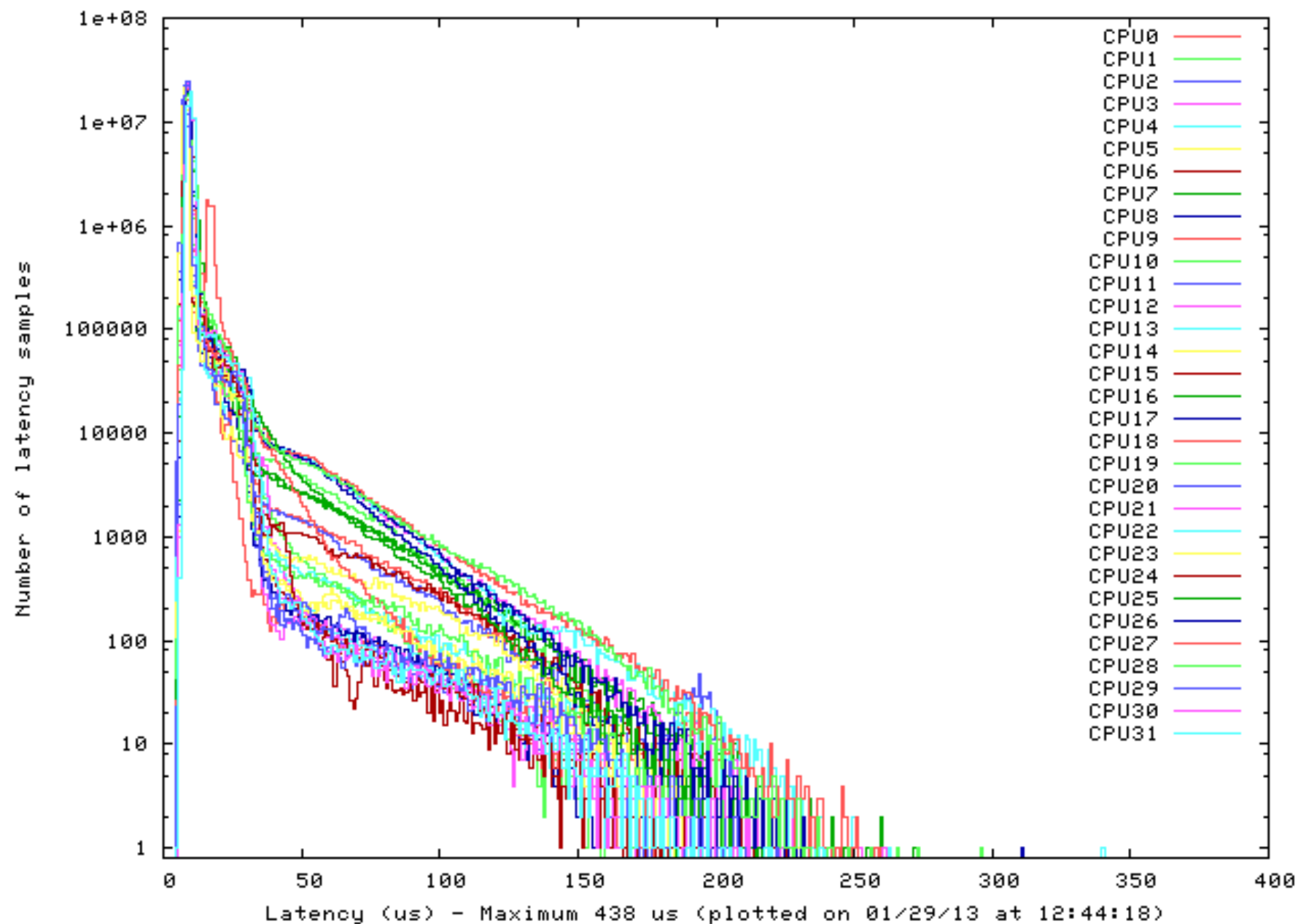
Picked from the OSADL spaghetti graph



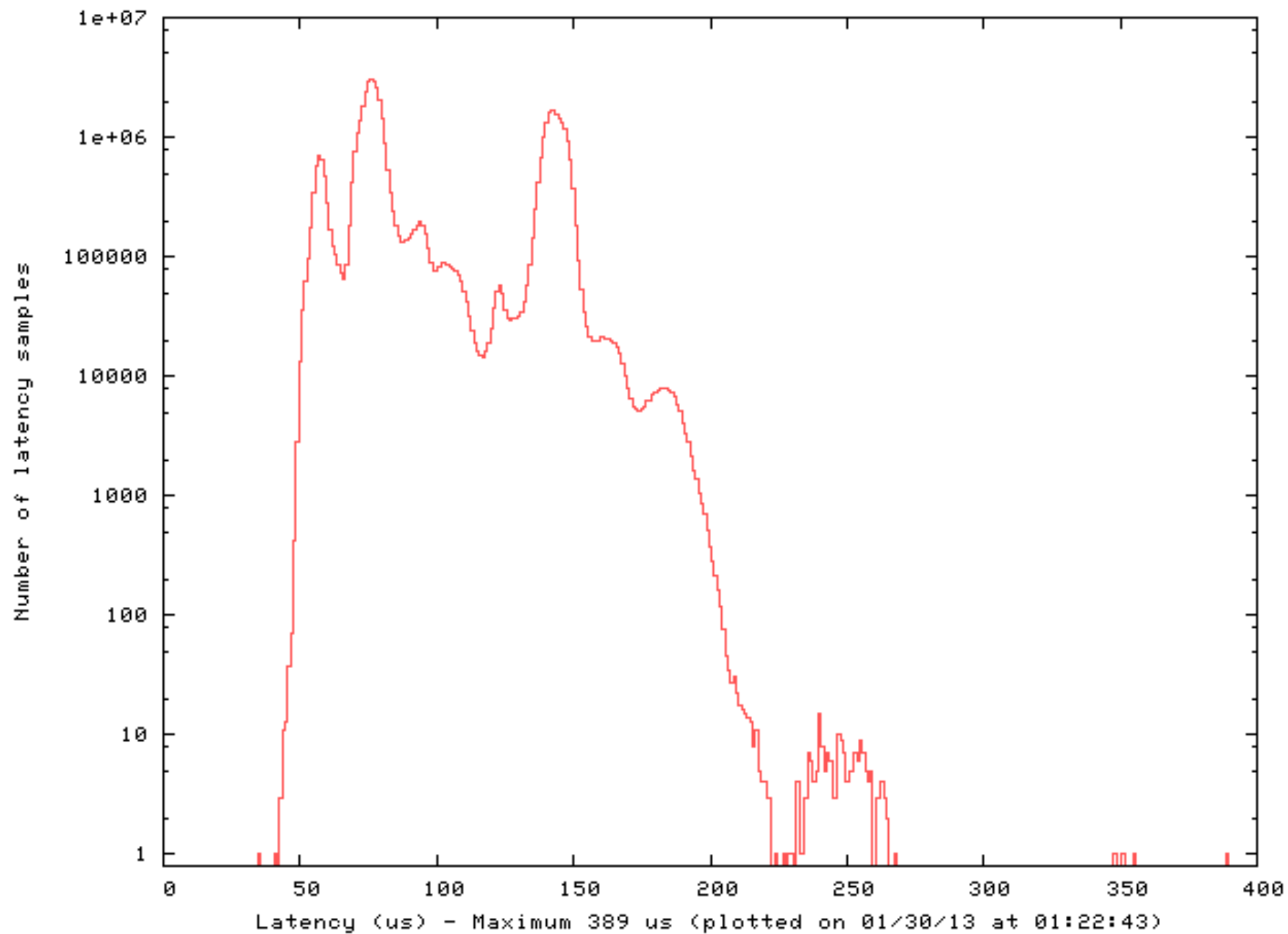
Latency rack0slot5

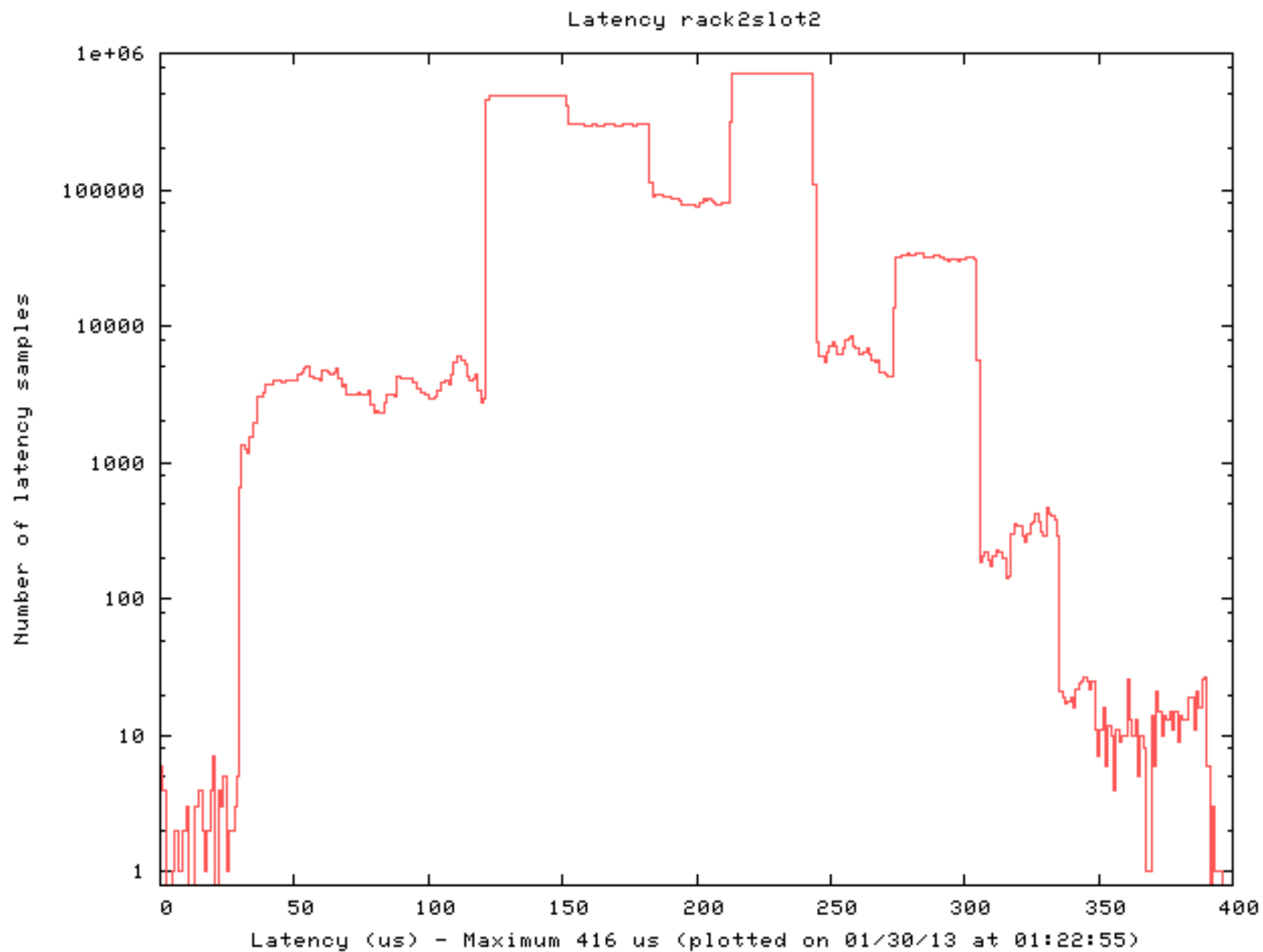


Latency rack1slot1

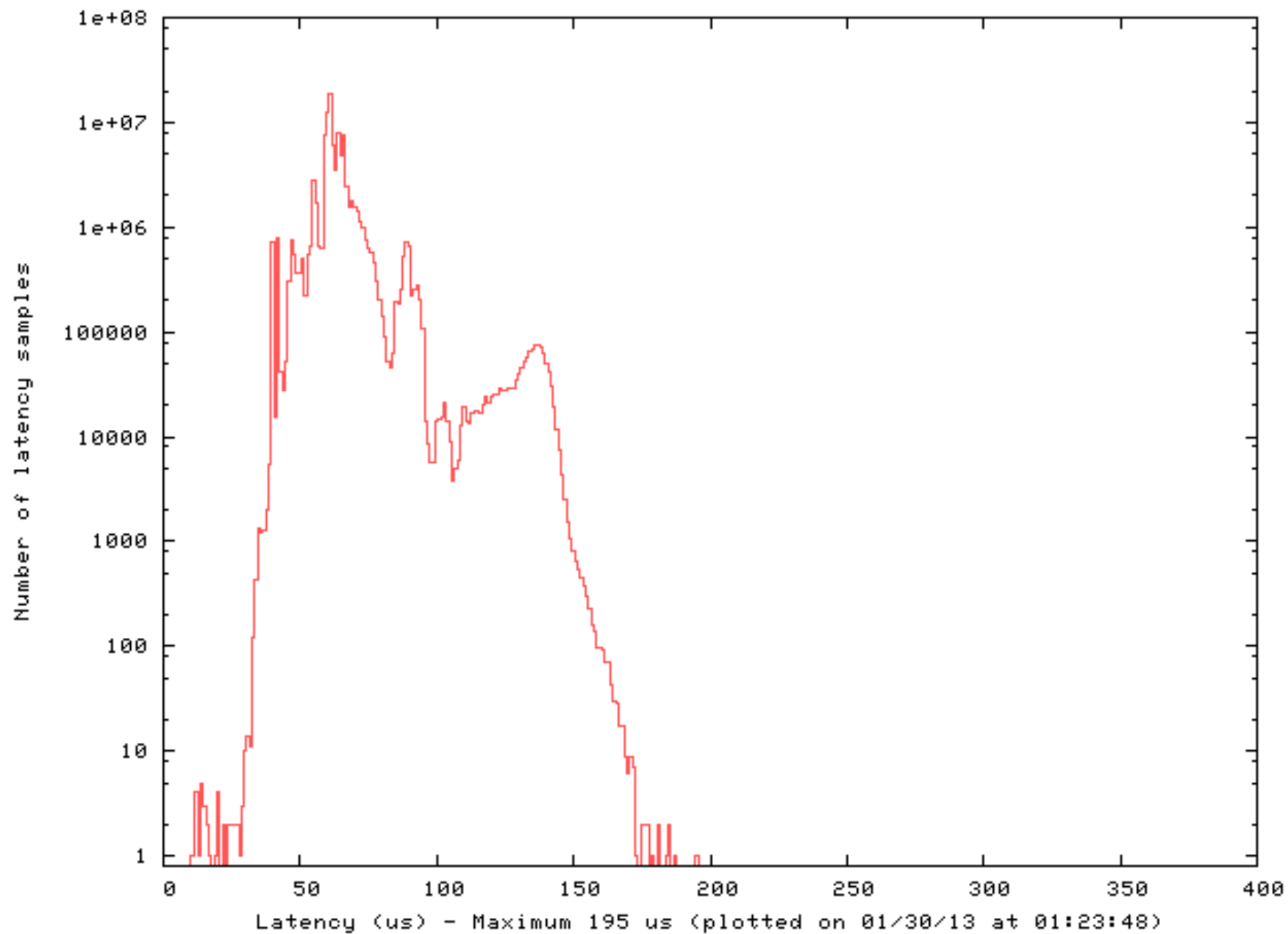


Latency rack2slot1

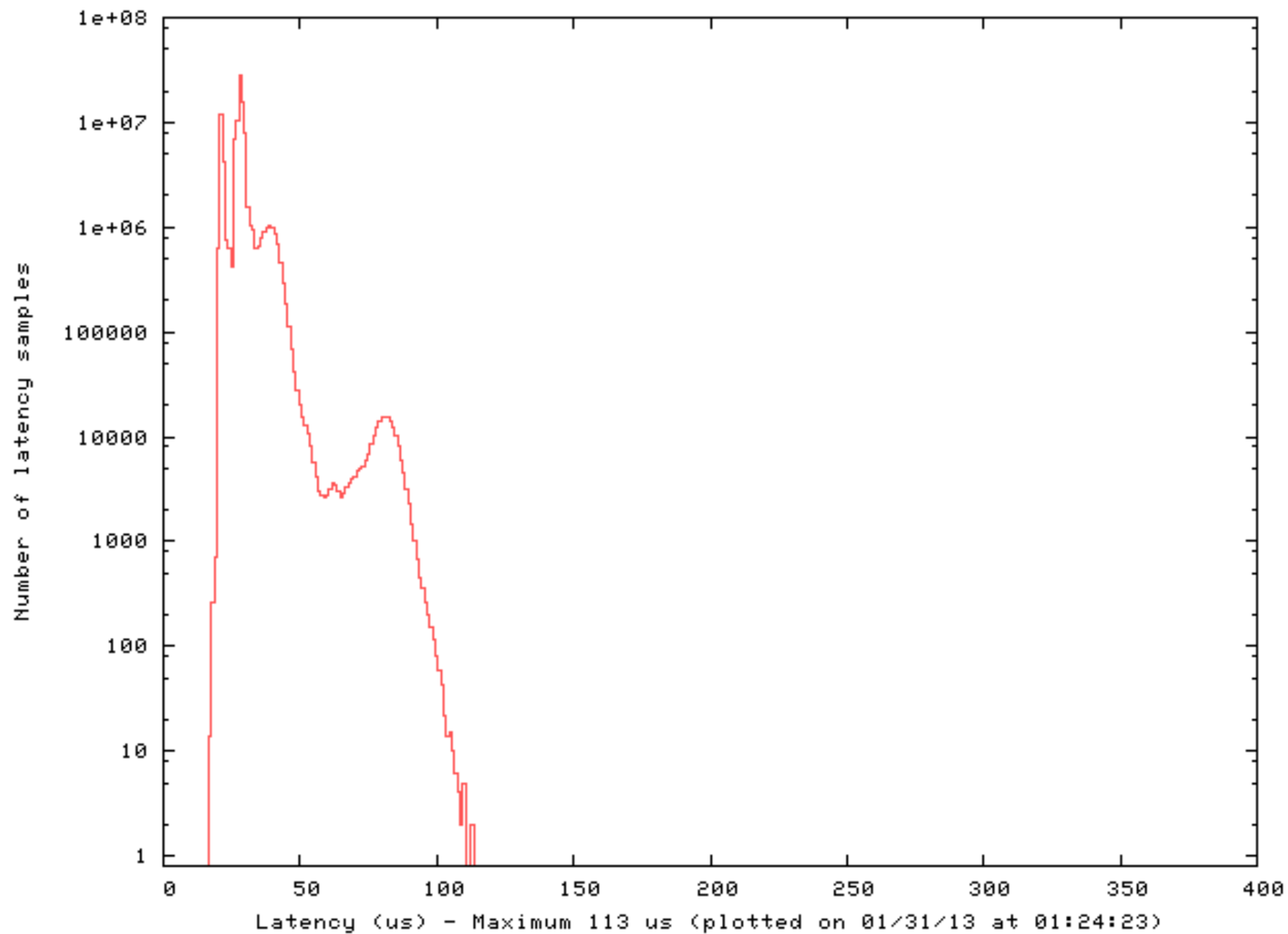




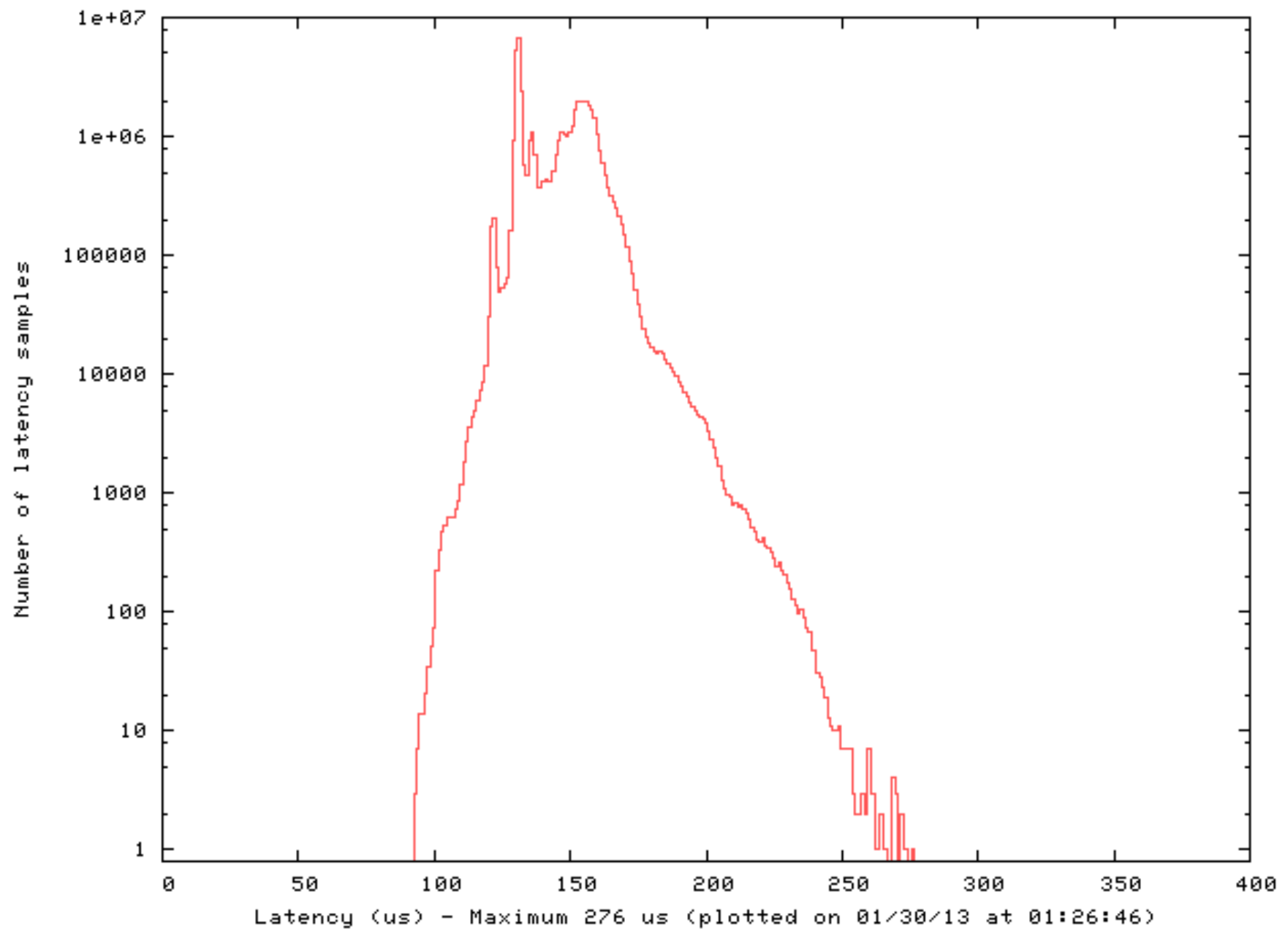
Latency rack2slot5



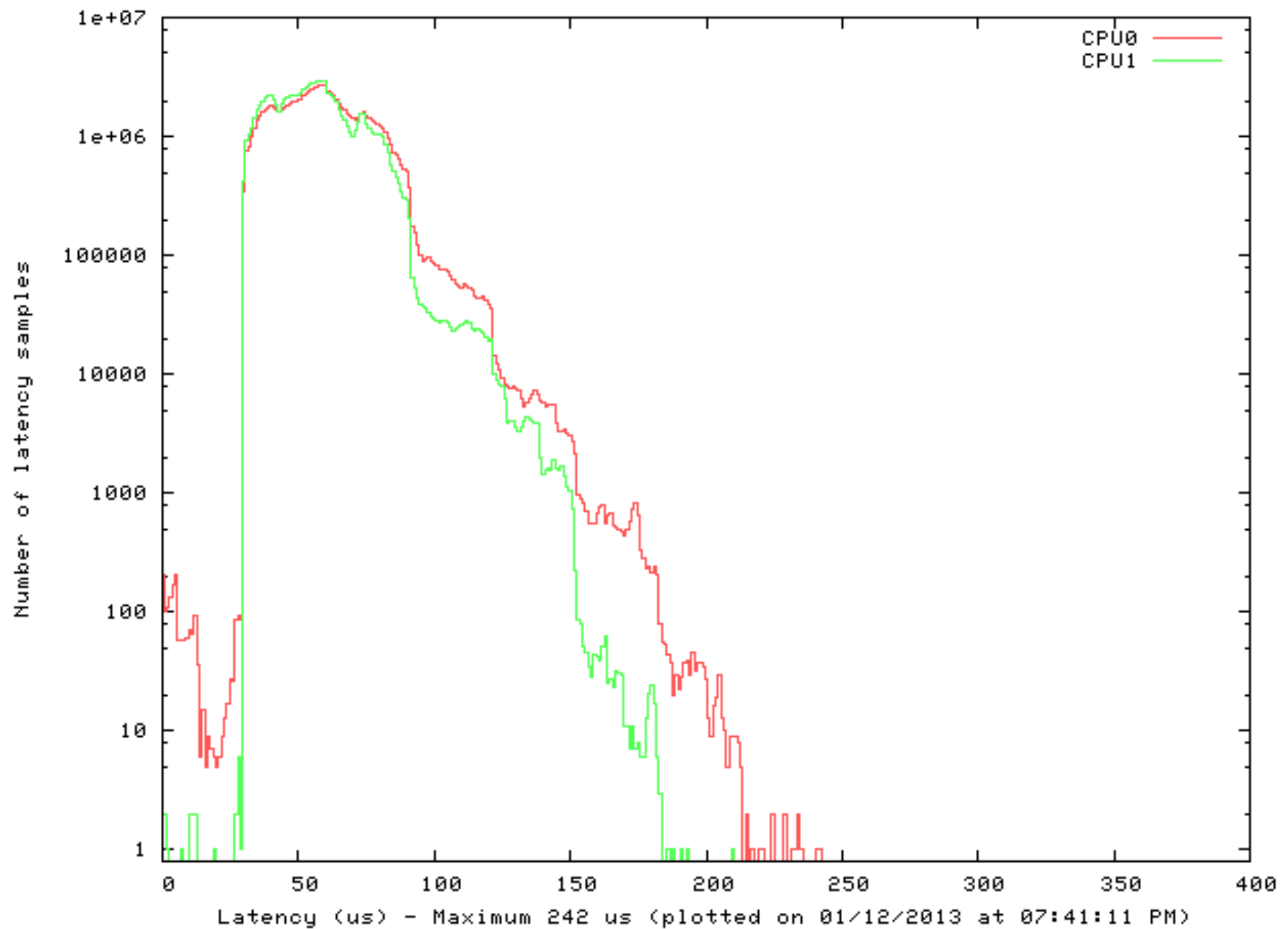
Latency rack2slot8



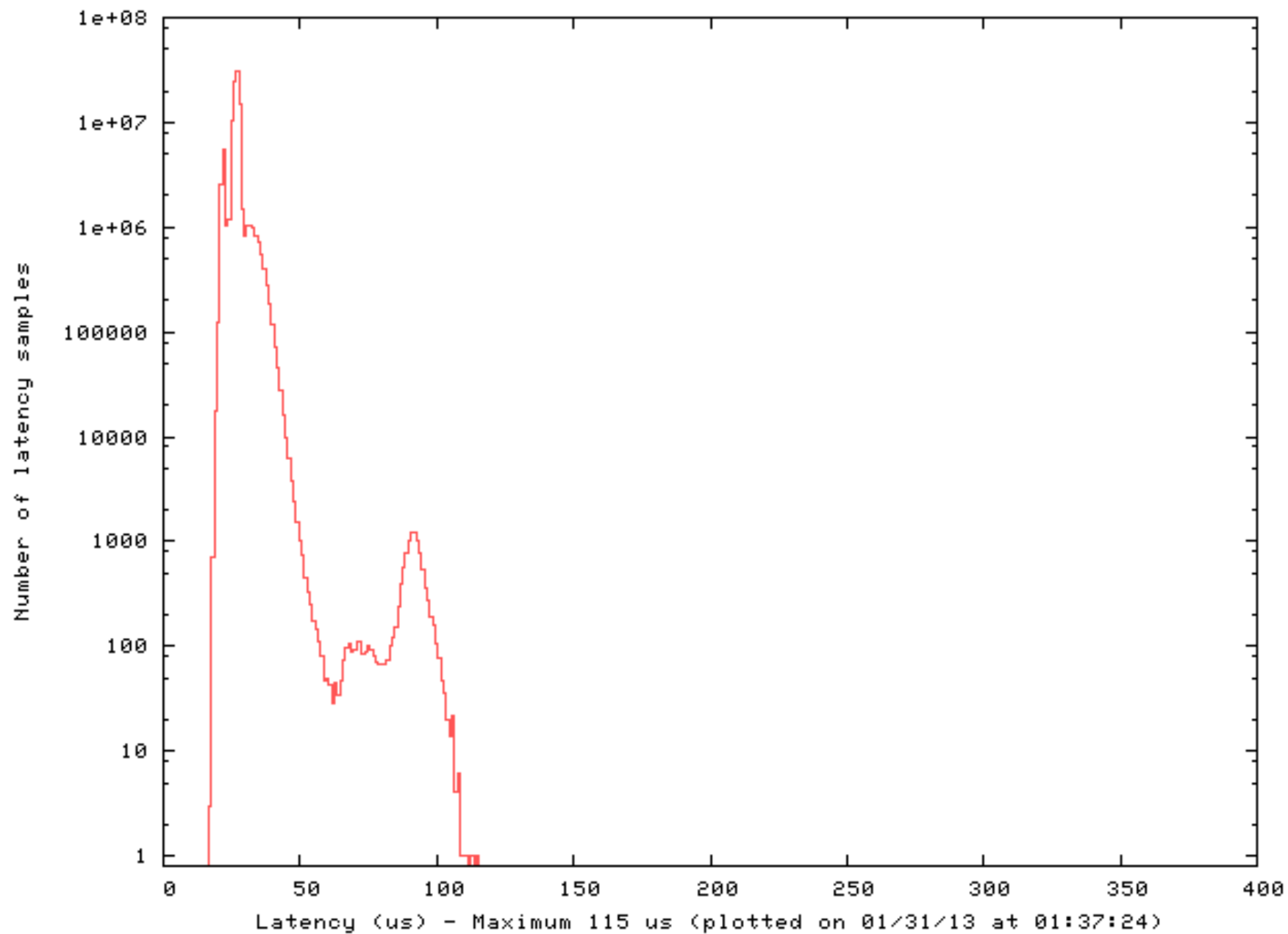
Latency rack3slot5



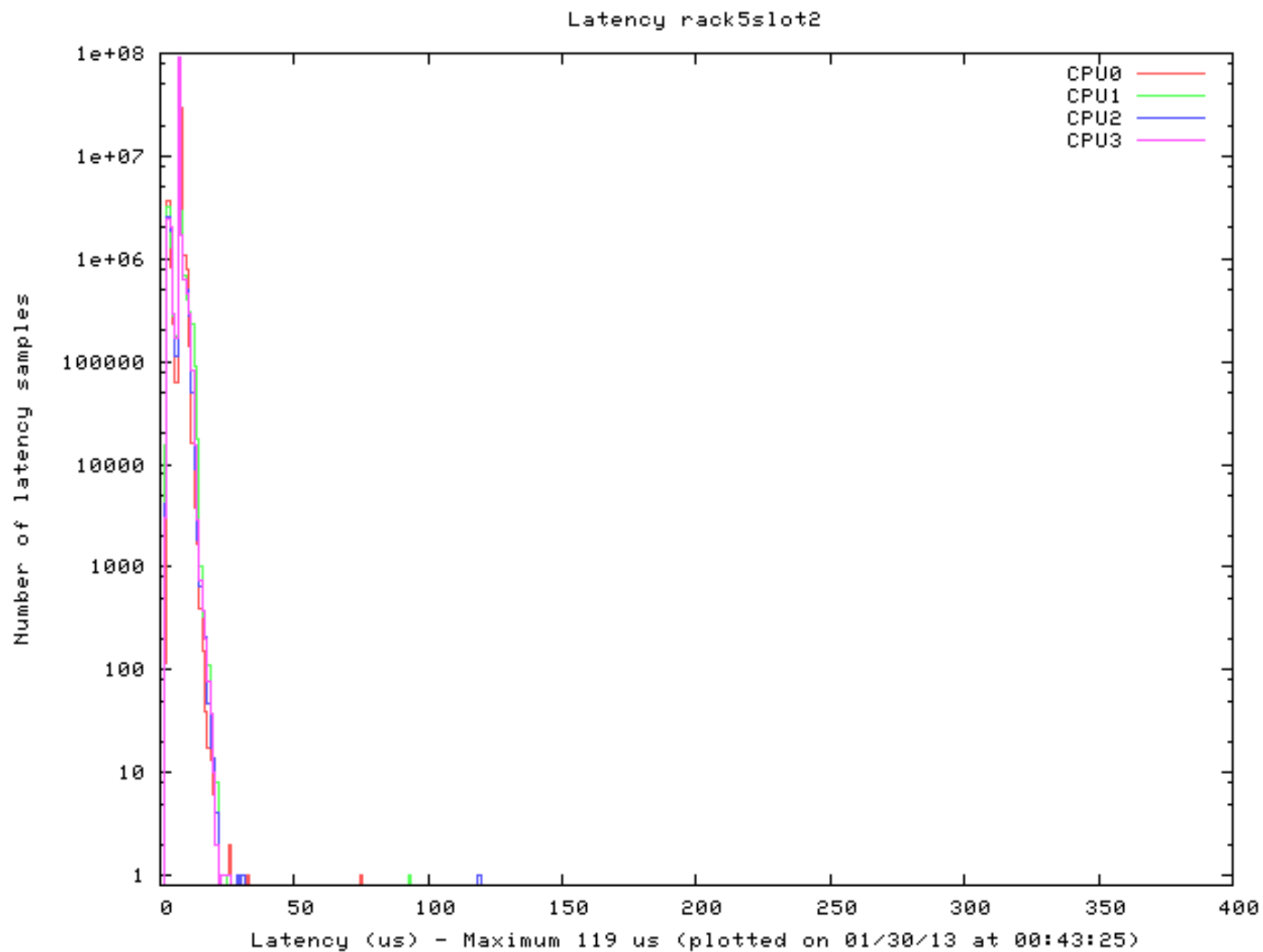
Latency rack4slot4



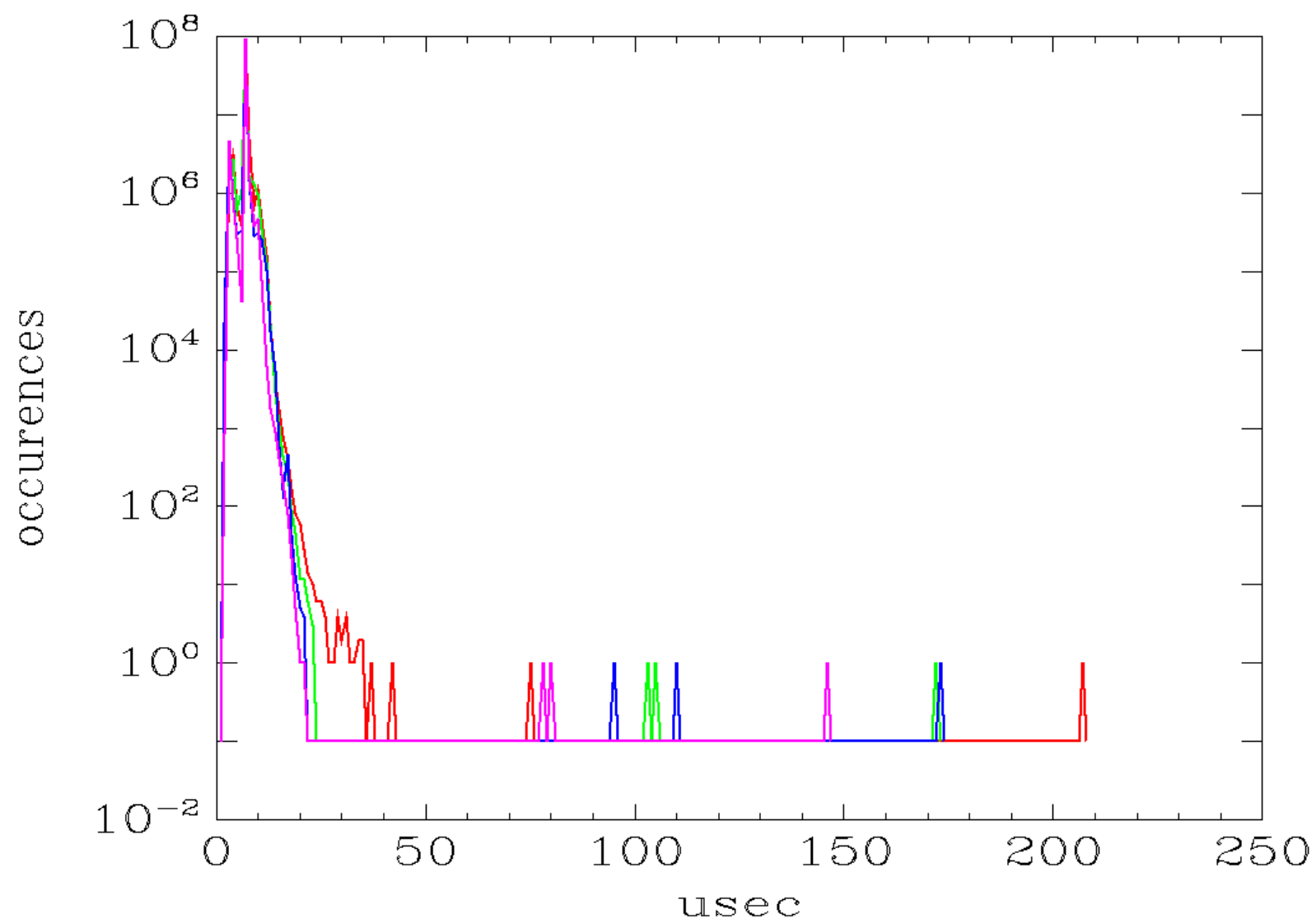
Latency rack7slot5



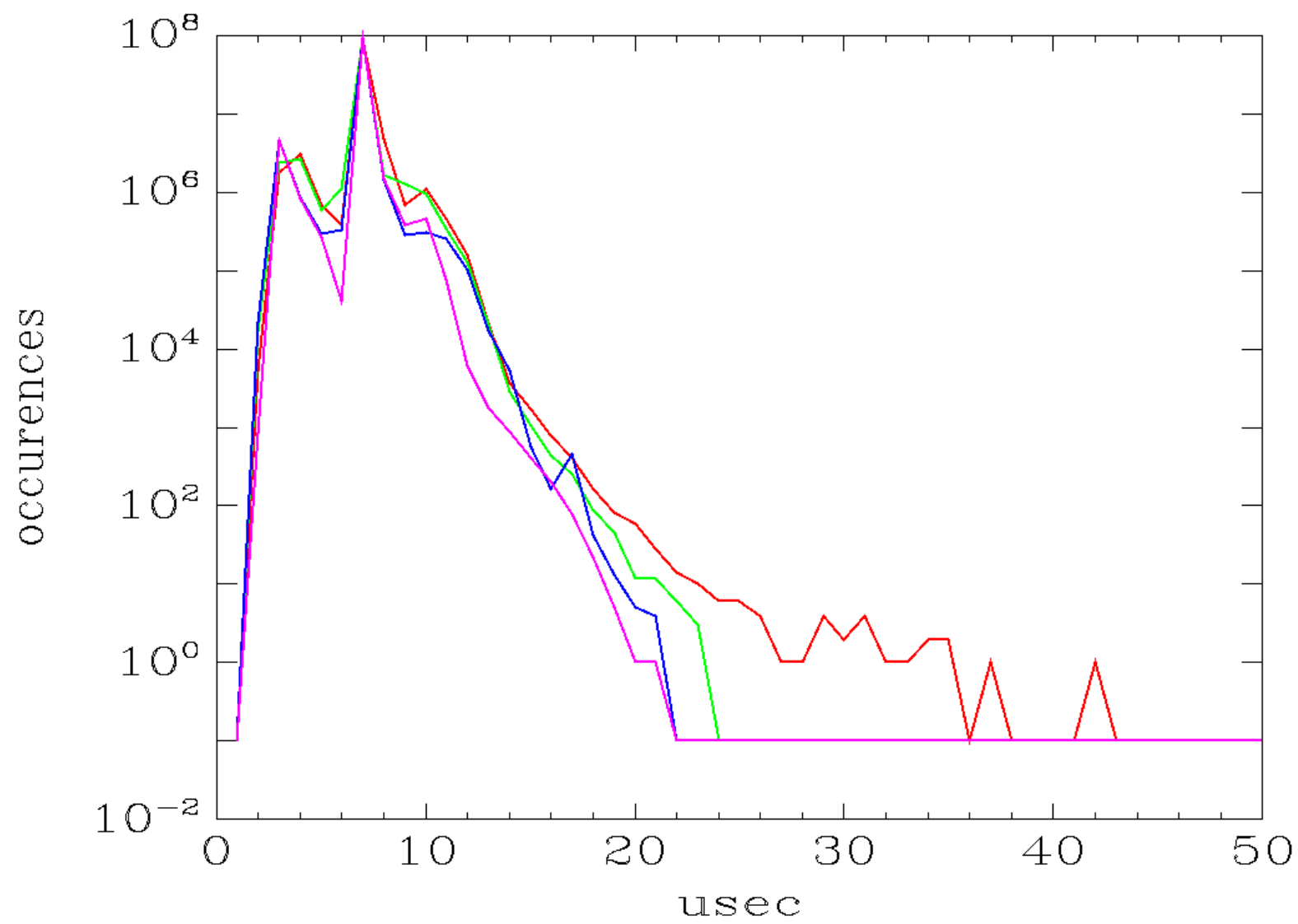
Even “boring” graphs may
contain interesting details



Latency rack5slot2
r5s2-2013-01-30-13



Latency rack5slot2
r5s2-2013-01-30-13



Command Line Options

An unruly, out of control, set of control knobs

```

$ cyclicttest --help
cyclicttest V 0.85
Usage:
cyclicttest <options>

-a [NUM] --affinity          run thread #N on processor #N, if possible
                             with NUM pin all threads to the processor NUM
-b USEC --breaktrace=USEC   send break trace command when latency > USEC
-B --preemptirqs            both preempt and irqsoff tracing (used with -b)
-c CLOCK --clock=CLOCK      select clock
                             0 = CLOCK_MONOTONIC (default)
                             1 = CLOCK_REALTIME
-C --context                context switch tracing (used with -b)
-d DIST --distance=DIST     distance of thread intervals in us default=500
-D --duration=t             specify a length for the test run
                             default is in seconds, but 'm', 'h', or 'd' maybe added
                             to modify value to minutes, hours or days
-e --latency=PM_QOS         write PM_QOS to /dev/cpu_dma_latency
-E --event                  event tracing (used with -b)
-f --ftrace                 function trace (when -b is active)
-g MAX --of_max=MAX         Report time in ms (up to MAX) for histogram overflows
-h --histogram=US           dump a latency histogram to stdout after the run
                             (with same priority about many threads)
                             US is the max time to be tracked in microseconds
-H --histofall=US          same as -h except with an additional summary column
-i INTV --interval=INTV    base interval of thread in us default=1000
-I --irqsoff                Irqsoff tracing (used with -b)
-l LOOPS --loops=LOOPS     number of loops: default=0(endless)
-m --mlockall               lock current and future memory allocations
-M --refresh_on_max         delay updating the screen until a new max latency is hit
-n --nanosleep              use clock_nanosleep
-N --nsecs                  print results in ns instead of us (default us)
-o RED --oscope=RED         oscilloscope mode, reduce verbose output by RED
-O TOPT --traceopt=TOPT    trace option
-p PRIO --prio=PRIO         priority of highest prio thread
-P --preemptoff             Preempt off tracing (used with -b)
-q --quiet                  print only a summary on exit
-Q --priospread             spread priority levels starting at specified value
-r --relative               use relative timer instead of absolute
-R --resolution             check clock resolution, calling clock_gettime() many
                             times. list of clock_gettime() values will be
                             reported with -X
-s --system                 use sys_nanosleep and sys_setitimer
-S --smp                    Standard SMP testing: options -a -t -n and
                             same priority of all threads
-t --threads                one thread per available processor
-t [NUM] --threads=NUM     number of threads:
                             without NUM, threads = max_cpus
                             without -t default = 1
-T TRACE --tracer=TRACER   set tracing function
                             configured tracers: blk function_graph wakeup_rt wakeup function nop
-u --unbuffered             force unbuffered output for live processing
-U --numa                   Standard NUMA testing (similar to SMP option)
                             thread data structures allocated from local node
-v --verbose                output values on stdout for statistics
                             format: n:c:v n=tasknum c=count v=value in us
-w --wakeup                 task wakeup tracing (used with -b)
-W --wakeuprt               rt task wakeup tracing (used with -b)
-X --dbg_cyclicttest        print info useful for debugging cyclicttest
-y POLI --policy=POLI      policy of realtime thread, POLI may be fifo(default) or rr
                             format: --policy=fifo(default) or --policy=rr

```

Thread Behavior Options

-a [NUM]	--affinity	run thread #N on processor #N, if possible with NUM pin all threads to the processor NUM
-c CLOCK	--clock=CLOCK	select clock 0 = CLOCK_MONOTONIC (default) 1 = CLOCK_REALTIME
-d DIST	--distance=DIST	distance of thread intervals in us default=500
-i INTV	--interval=INTV	base interval of thread in us default=1000
-m	--mlockall	lock current and future memory allocations
-n	--nanosleep	use clock_nanosleep
-p PRIO	--prio=PRIO	priority of highest prio thread
-Q	--priospread	spread priority levels starting at specified value
-r	--relative	use relative timer instead of absolute
-s	--system	use sys_nanosleep and sys_setitimer
-S	--smp	Standard SMP testing: options -a -t -n and same priority of all threads
-t	--threads	one thread per available processor
-t [NUM]	--threads=NUM	number of threads: without NUM, threads = max_cpus without -t default = 1
-U	--numa	Standard NUMA testing (similar to SMP option) thread data structures allocated from local node
-y POLI	--policy=POLI	policy of realtime thread, POLI may be fifo(default) or rr format: --policy=fifo(default) or --policy=rr

side effect, sets -d0

-h	--histogram=US	dump a latency histogram to stdout after the run (with same priority about many threads) US is the max time to be tracked in microseconds
-H	--histofall=US	same as -h except with an additional summary column

Benchmark and System Options

- D   --duration=t   specify a length for the test run
                                      default is in seconds, but 'm', 'h', or 'd' maybe added
                                      to modify value to minutes, hours or days
- l LOOPS --loops=LOOPS   number of loops: default=0(endless)
- e   --latency=PM_QOS   write PM_QOS to /dev/cpu_dma_latency

Display Options

-g MAX	--of_max=MAX	Report time in ms (up to MAX) for histogram overflows
-h	--histogram=US	dump a latency histogram to stdout after the run (with same priority about many threads) US is the max time to be tracked in microseconds
-H	--histofall=US	same as -h except with an additional summary column
-M	--refresh_on_max	delay updating the screen until a new max latency is hit
-N	--nsecs	print results in ns instead of us (default us)
-o RED	--oscope=RED	oscilloscope mode, reduce verbose output by RED
-q	--quiet	print only a summary on exit
-u	--unbuffered	force unbuffered output for live processing
-v	--verbose	output values on stdout for statistics

format: n:c:v n=tasknum c=count v=value in us

Debug Options

-b USEC --breaktrace=USEC send break trace command when latency > USEC
-B --preemptirqs both preempt and irqsoff tracing (used with -b)
-C --context context switch tracing (used with -b)
-E --event event tracing (used with -b)
-f --ftrace function trace (when -b is active)
-I --irqsoff Irqsoff tracing (used with -b)
-O TOPT --traceopt=TOPT trace option
-P --preemptoff Preempt off tracing (used with -b)
-R --resolution check clock resolution, calling clock_gettime() many times. list of clock_gettime() values will be reported with -X

-T TRACE --tracer=TRACER set tracing function
    configured tracers: blk function_graph wakeup_rt wakeup function nop
-w --wakeup task wakeup tracing (used with -b)
-W --wakeuprt rt task wakeup tracing (used with -b)
-X --dbg_cyclictest print info useful for debugging cyclictest

Debug Options

No time to describe in this talk

Hooks to invoke various tools that can capture the cause of large latencies

Options Trivia

Options parsing is not robust - example 1

affinity will be 0

```
$ cyclicttest -t -l100 -a0
```

```
$ cyclicttest -t -l100 -a 0
```

```
$ cyclicttest -t -l100 -a7 -a0
```

affinity will be 7, with no error message

```
$ cyclicttest -t -l100 -a7 -a 0
```

-a   cpu affinity

Options Trivia

Options parsing is not robust - example 2

```
$ cyclictest -ant
```

```
T: 0 (26978) P: 0 I:1000 C: 2091 Min:
```

```
$ cyclictest -an -t
```

```
T: 0 (26980) P: 0 I:1000 C: 1928 Min:
```

```
T: 1 (26981) P: 0 I:1500 C: 1285 Min:
```

```
-a  cpu affinity
```

```
-n  clock_nanosleep()
```

```
-t  one thread per cpu
```

Options Trivia

Options parsing is not robust

Best Practice:

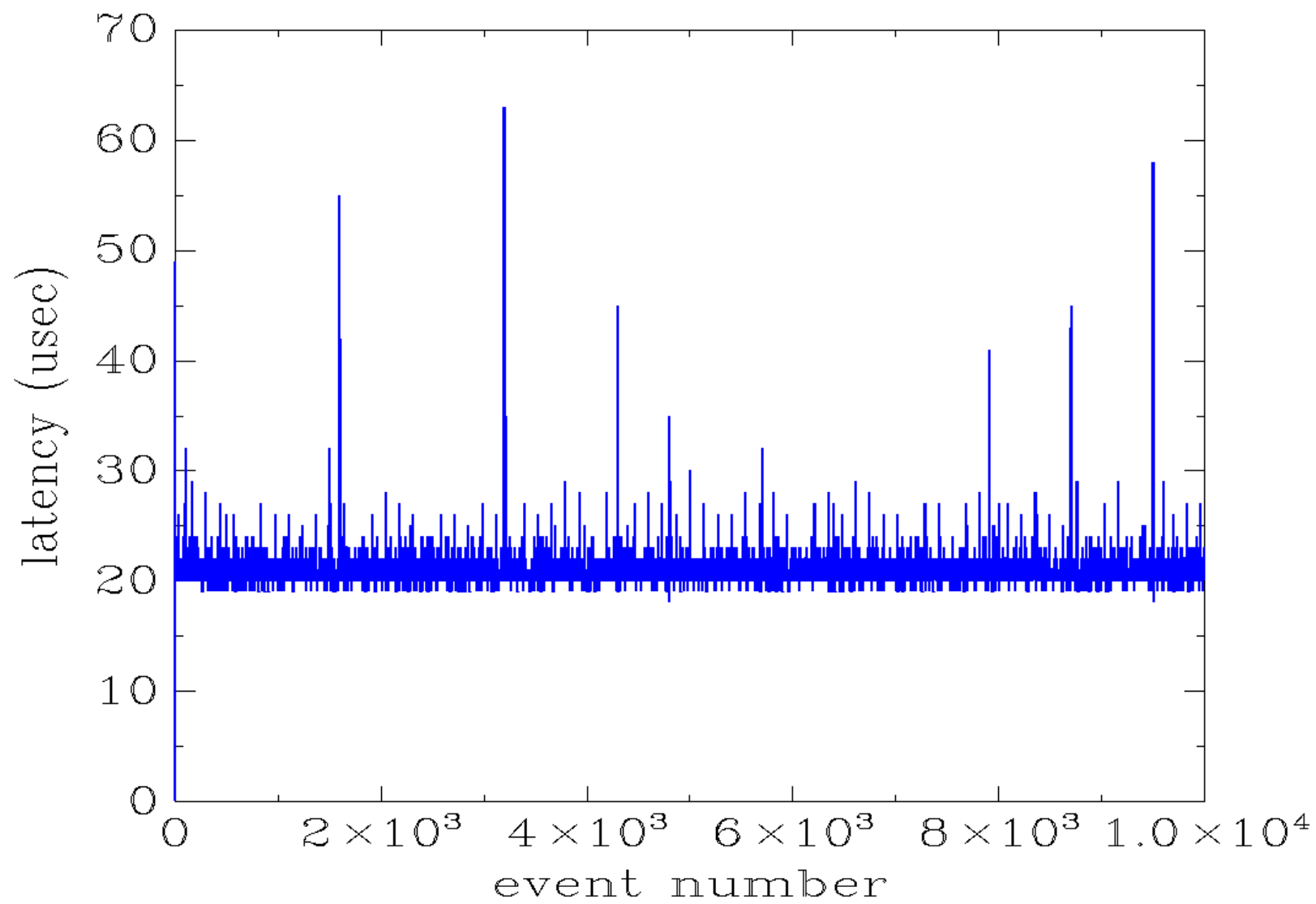
- do not combine options
- specify each separately with a leading "-"

Third Data Format

Report each latency

```
$ cyclicttest -q -n -t1 -p 48 -l 10000 -v
```

Cyclictest Latency
pri=51 ping flood



Hitting the RT sched throttle

/proc/sys/kernel/sched_rt_runtime_us

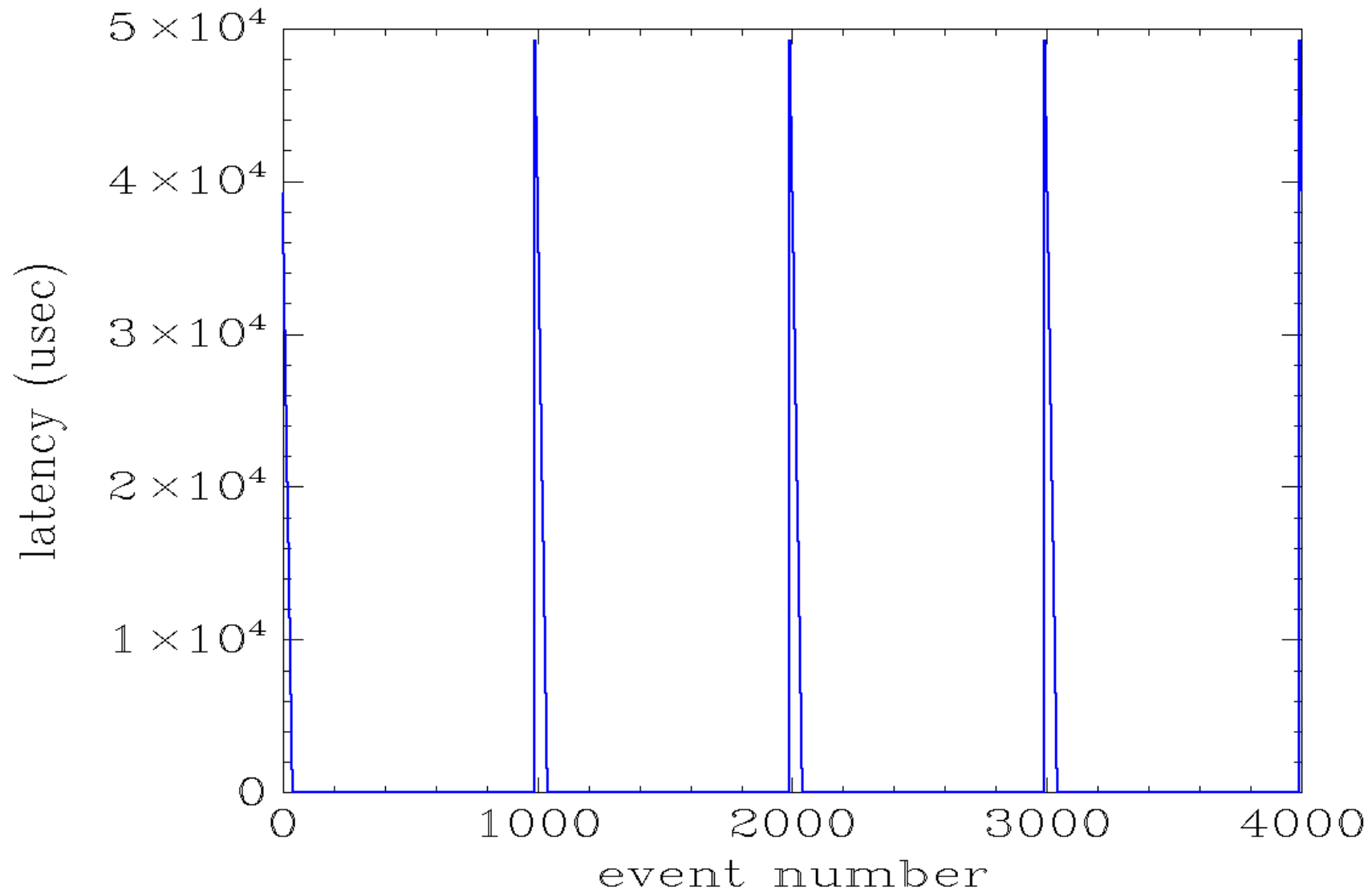
/proc/sys/kernel/sched_rt_period_us

cyclicttest: SCHED_FIFO priority=80

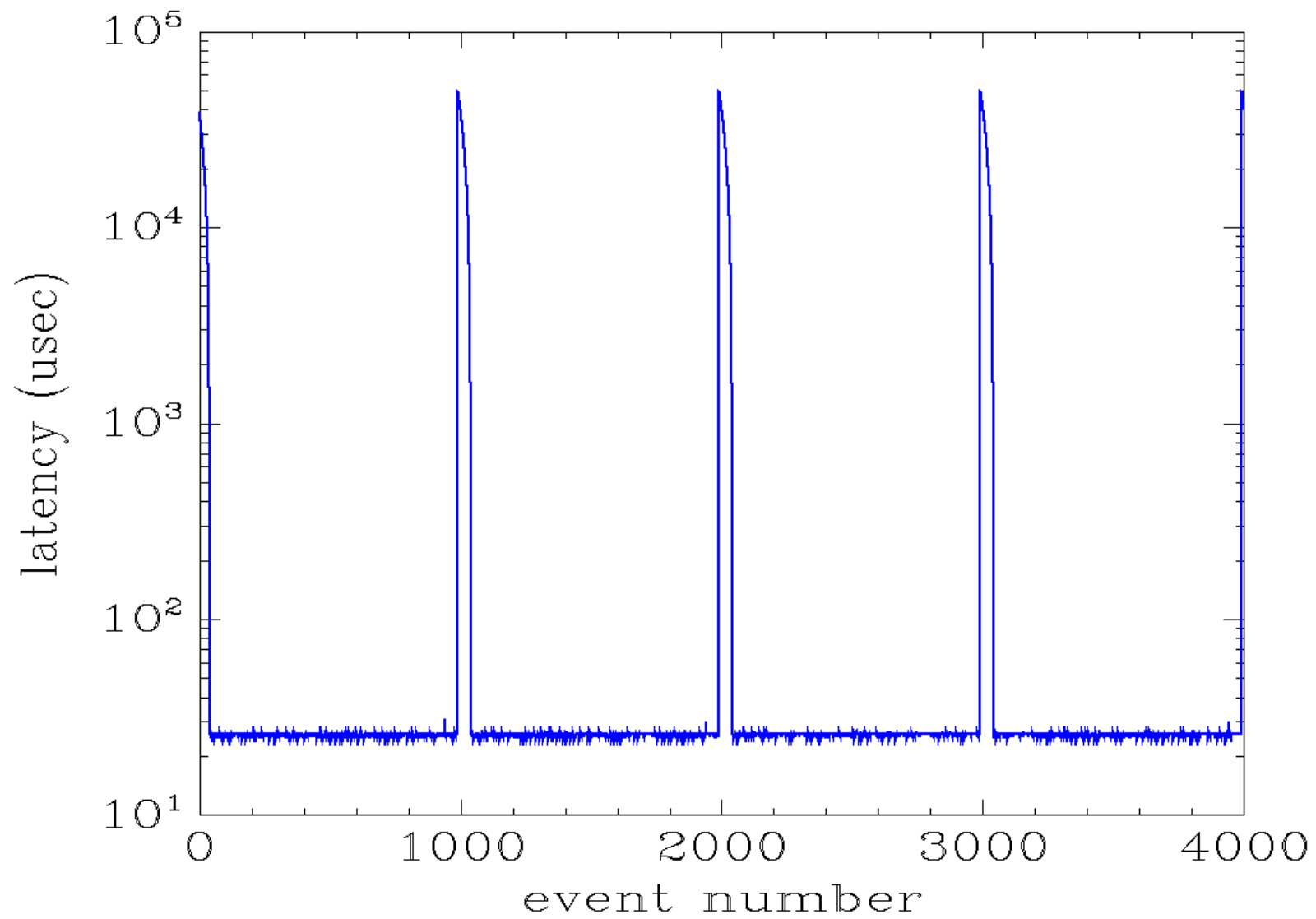
background load:

- continuous
- SCHED_FIFO priority=40

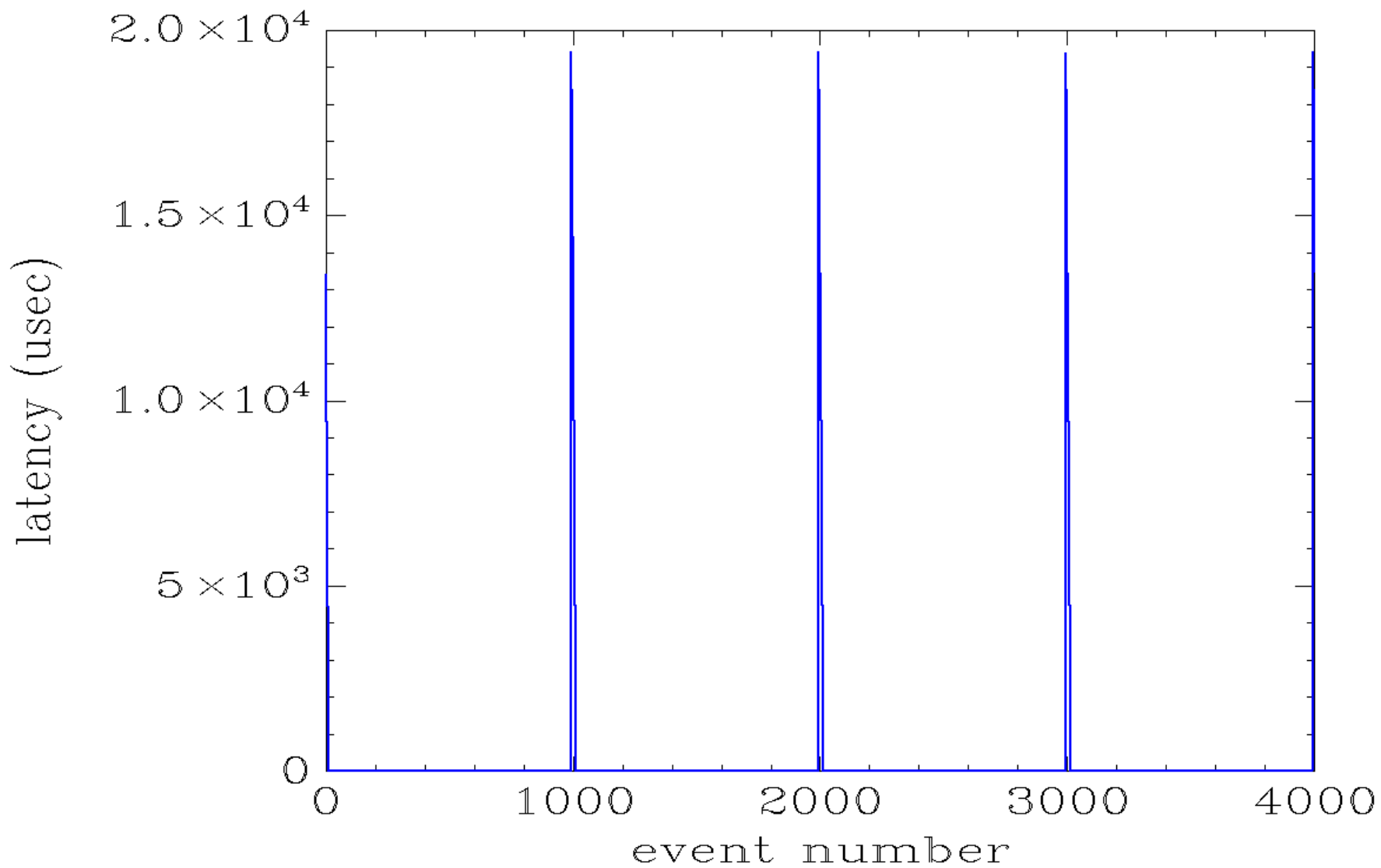
`sched_rt_runtime_us 80%`
`cyclicttest: SCHED_FIFO pri 80`



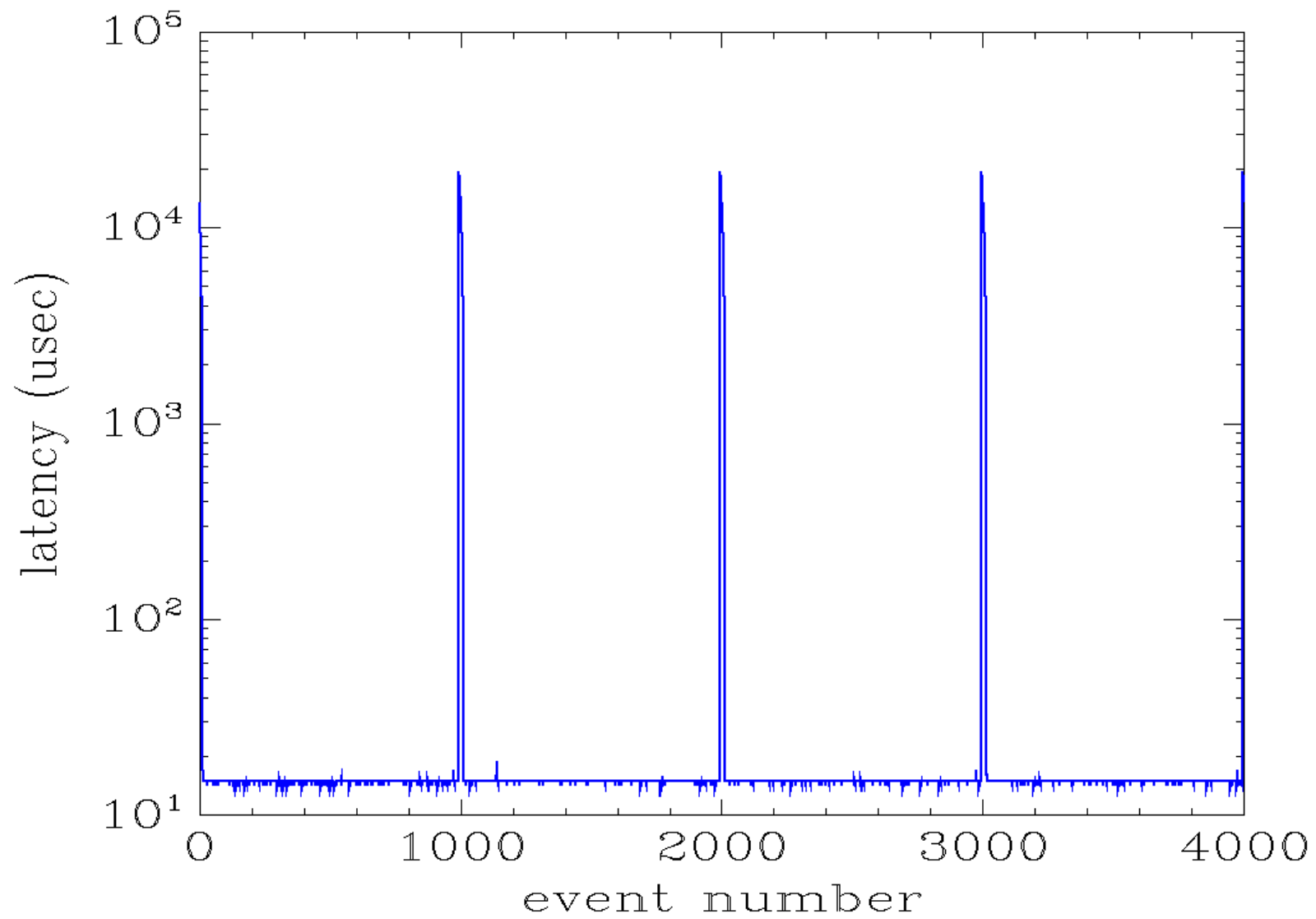
sched_rt_runtime_us 80%
cyclicttest: SCHED_FIFO pri 80



sched_rt_runtime_us=95_pct
cyclicttest: SCHED_FIFO pri 80



sched_rt_runtime_us=95_pct
cyclicttest: SCHED_FIFO pri 80



Hitting the RT sched throttle

/proc/sys/kernel/sched_rt_runtime_us

/proc/sys/kernel/sched_rt_period_us

cyclicttest: SCHED_NORMAL

background load:

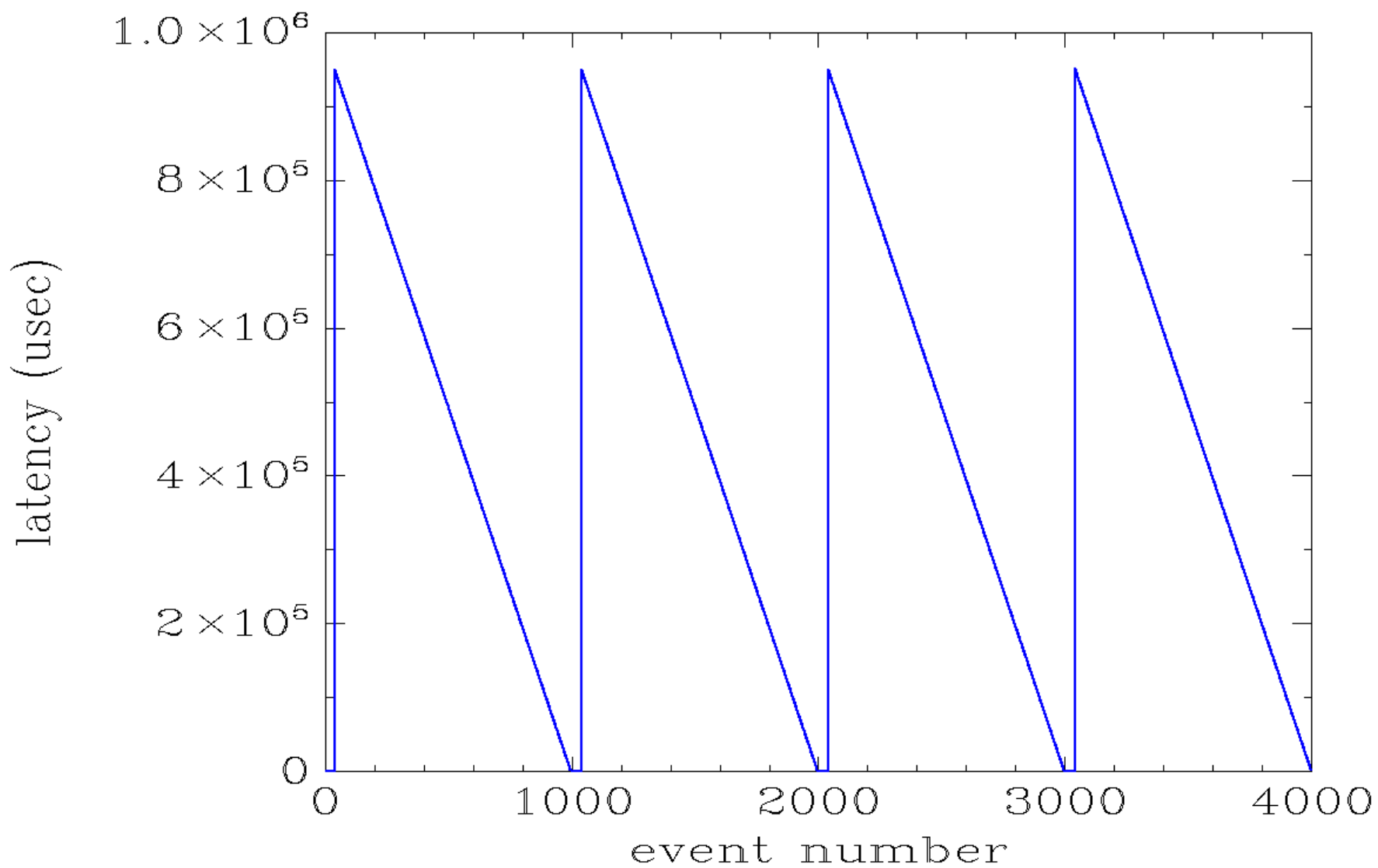
- continuous
- SCHED_FIFO priority=40

Hitting the RT sched throttle

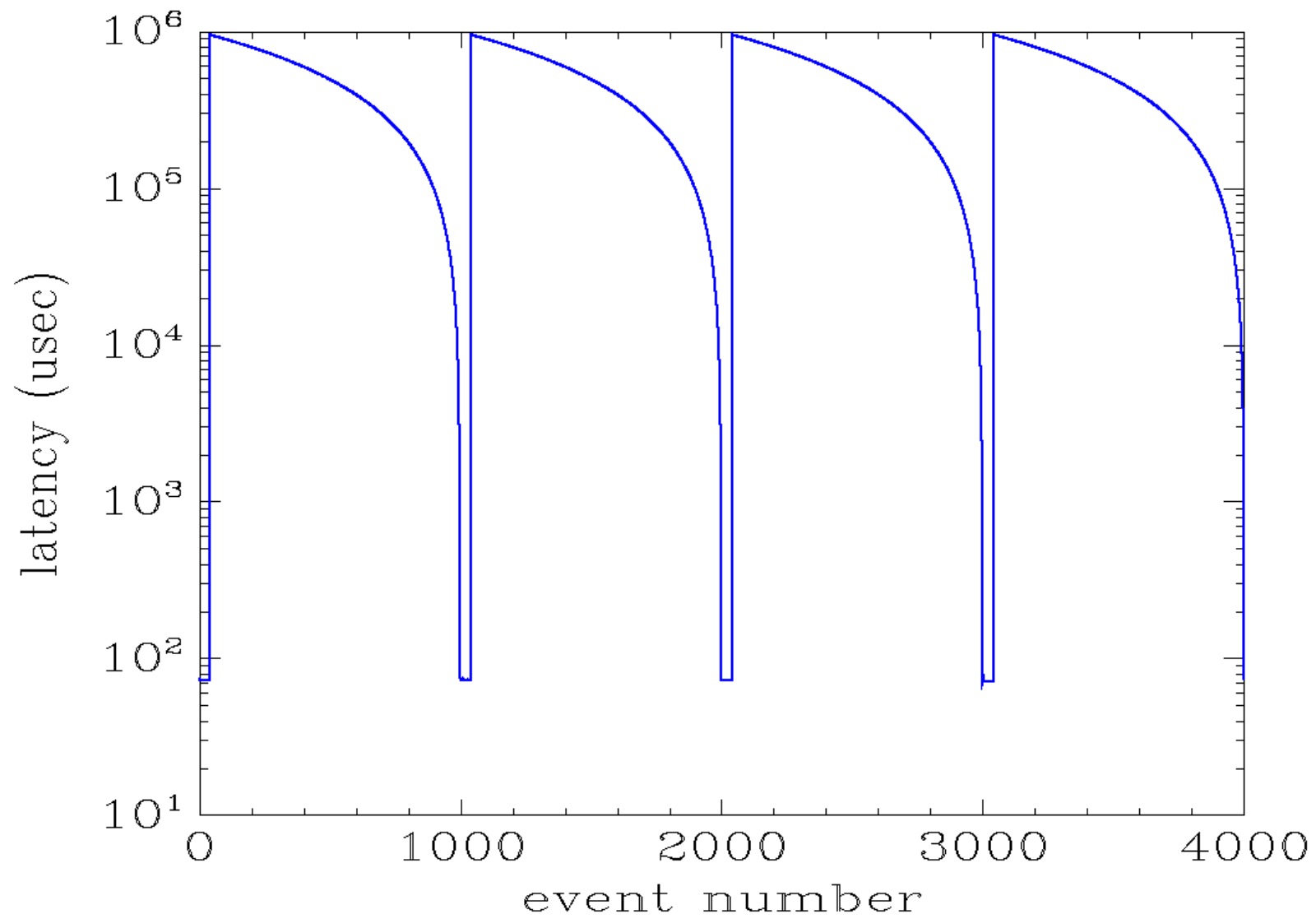
Why is this measurement interesting???

Gives a picture of how much cpu is NOT used by the real time tasks

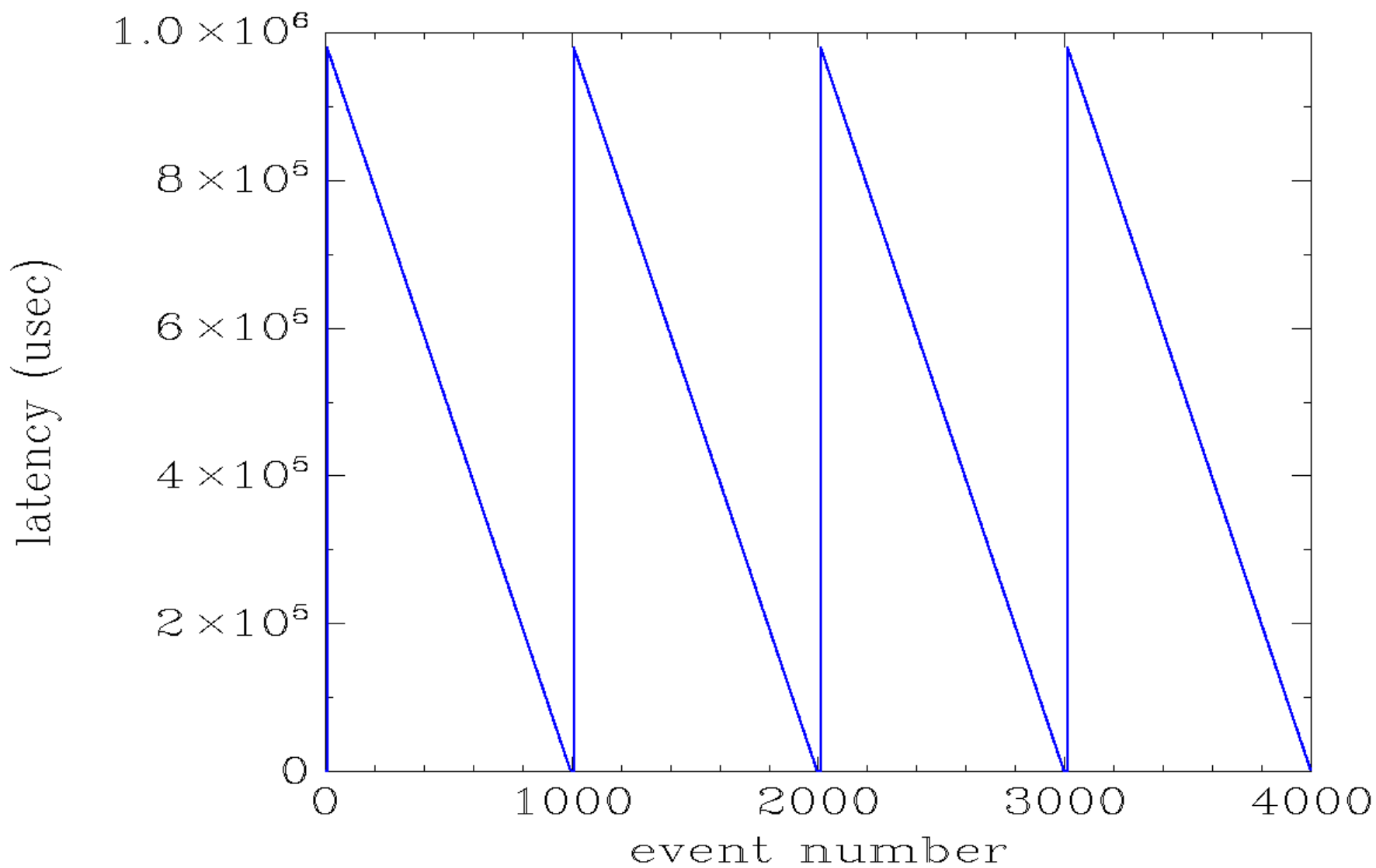
sched_rt_runtime_us 80%
cyclicttest: SCHED_NORMAL



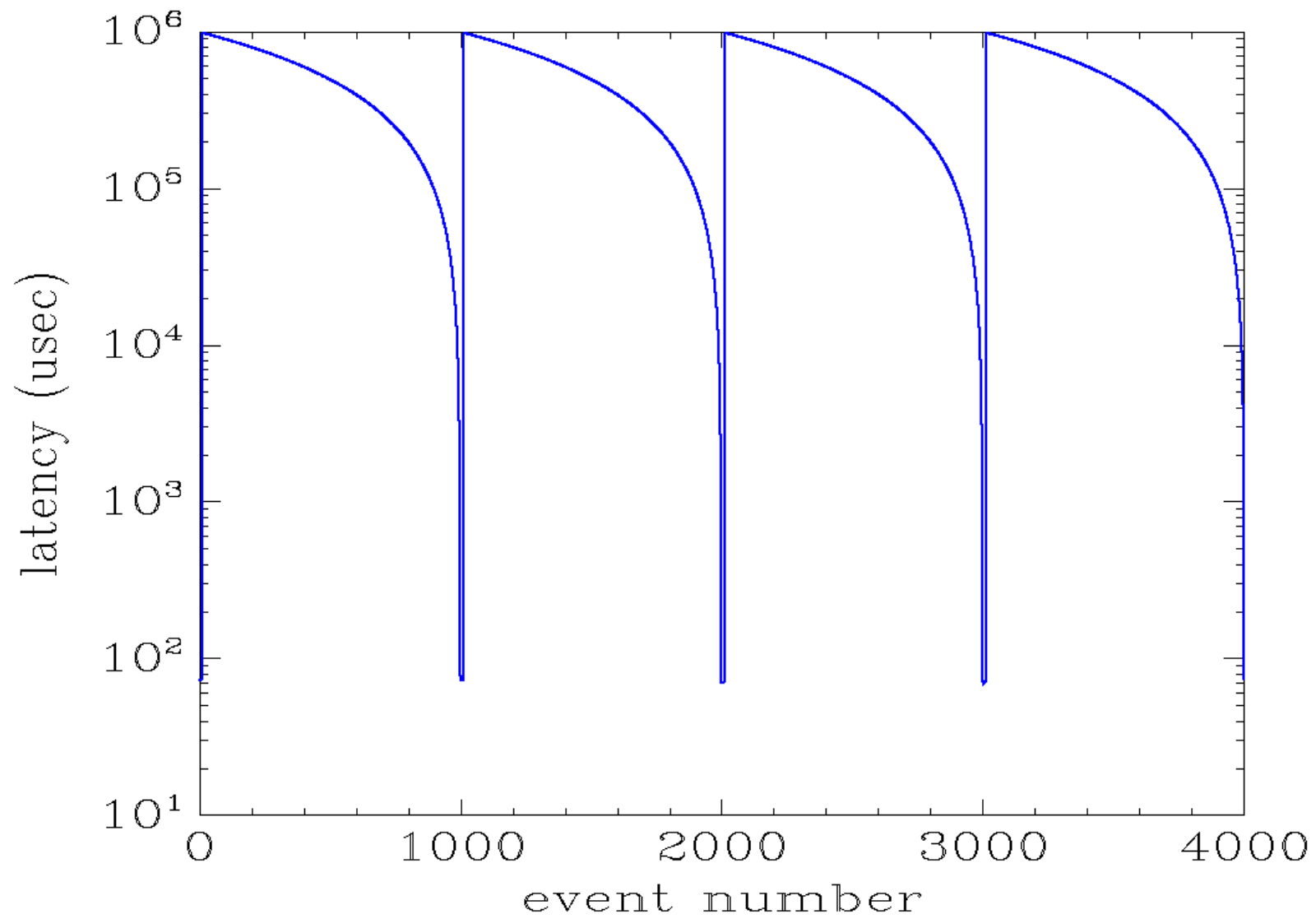
sched_rt_runtime_us 80%
cyclicttest: SCHED_NORMAL



sched_rt_runtime_us=95_pct
cyclicttest: SCHED_NORMAL



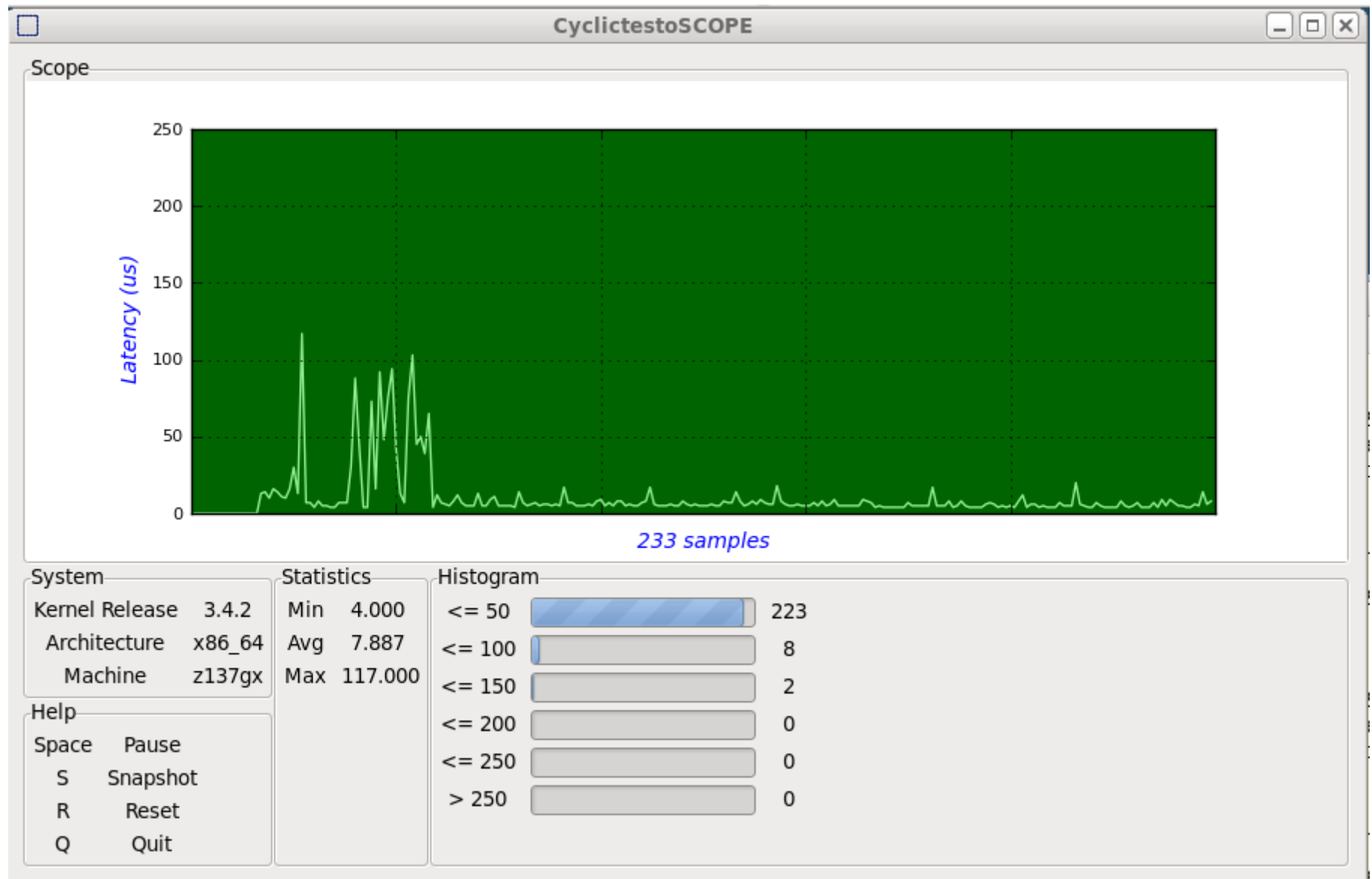
sched_rt_runtime_us=95_pct
cyclicttest: SCHED_NORMAL



Demo - oscilloscope

```
cyclictest_0.85 -t1 -n -p80 -i100 -o10 -v \  
| oscilloscope >/dev/null
```

oscilloscope screen shot



Fourth Data Format

Report time of each histogram overflow

Should be in next version of cyclicttest (0.86?)

```
$ cyclicttest -q -h 400 -g 1000
```

The same information can be extracted from the third data format (-v), but this method is lower overhead.

Finding and Building

```
git clone \
  git://git.kernel.org/pub/scm/linux/kernel/git/clkwillms/rt-tests.git
source: src/cyclictest/cyclictest.c
```

```
self-hosted:
  make
```

```
self-hosted without NUMA:
  make NUMA=0
```

```
cross-build without NUMA:
  make NUMA=0 CC="${CROSS_COMPILE}gcc"
```

Review

- Simple methodology captures all sources of latency fairly well
- Options must be used with care
- Options are powerful
- Different data formats are each useful
- Debug features can capture the cause of large latencies

THE END

Thank you for your attention...

Questions?

How to get a copy of the slides

- 1) leave a business card with me
- 2) frank.rowand@am.sony.com

